

# Building Reliable Activity Models Using Hierarchical Shrinkage and Mined Ontology

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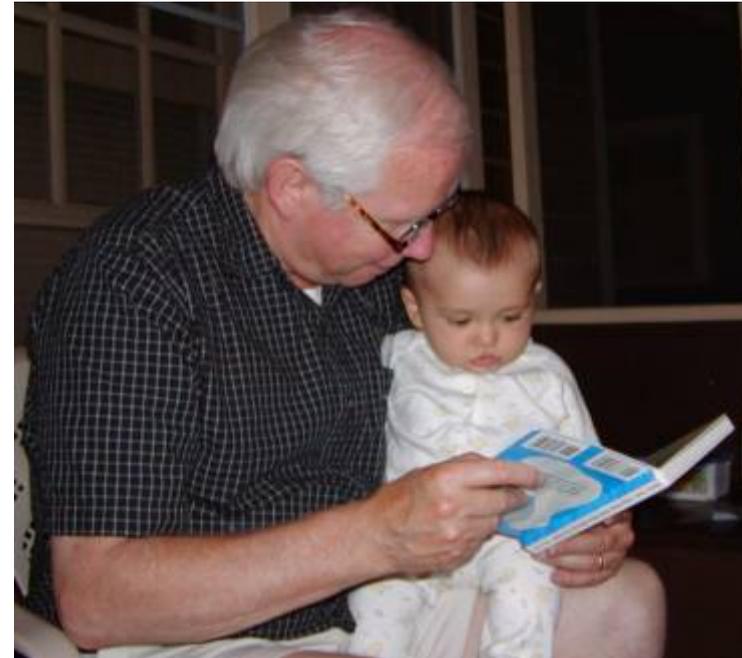
# Activity Recognition applications

- Activity-aware actuation
- Proactive reminding
- Ubiquitous healthcare
- Embedded health assessment



# Activities of Daily Living (ADLs)

Activity Class
Personal Appearance
Housework
Toileting
Washing up
Appliance Use
Taking care of an infant
Care of clothes and linen
Making a snack
Making a drink
Oral hygiene
... 23 classes, 1000s of activities



Classes of day-to-day activities that:

- Indicate cognitive well-being
- Indicate level of independence

e.g. Is elder still able to prepare a pasta?

What sensors could we use?



# Activity inference based on object use

Dense sensing: attach sensors directly to objects in the environment.

- Battery-free wireless stickers (RFIDs)
- Battery powered sensor nodes



# Activity inference based on object use

## Advantages

- Robust to environmental conditions
- High level information can be associated with the sensors



<ID = e3f000e13431, desc = "bread basket", manufacturer = "...", ... >

What inference algorithms could we use?



# Activity inference using Dynamic Bayesian networks (HMMs)

## Advantages

- Easy to incorporate common sense information
- Efficient inference algorithms

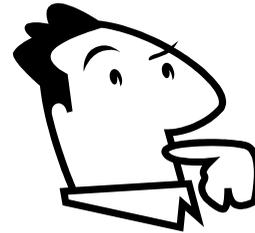
To create an activity model we need

- List of objects used while performing an activity
- Probability of using the objects

e.g  $p(\text{pot}|\text{cooking}) = 0.7$



# Techniques for constructing activity models: Hand definition



prepare pasta

list of objects

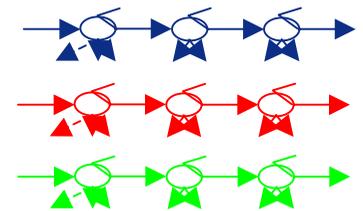
pot  
stove  
spoon  
spaghetti

probability of using objects

$P(\text{pot} \text{boiling pasta})$	0.2
$P(\text{stove} \text{boiling pasta})$	0.2
$P(\text{spoon} \text{boiling pasta})$	0.1
$P(\text{Spaghetti} \text{boiling pasta})$	0.5



models



# Techniques for constructing activity models: Learn from data

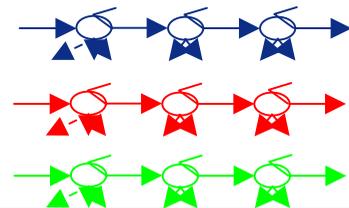
unlabeled data (objects used)

*label*

labeled data

*learn*

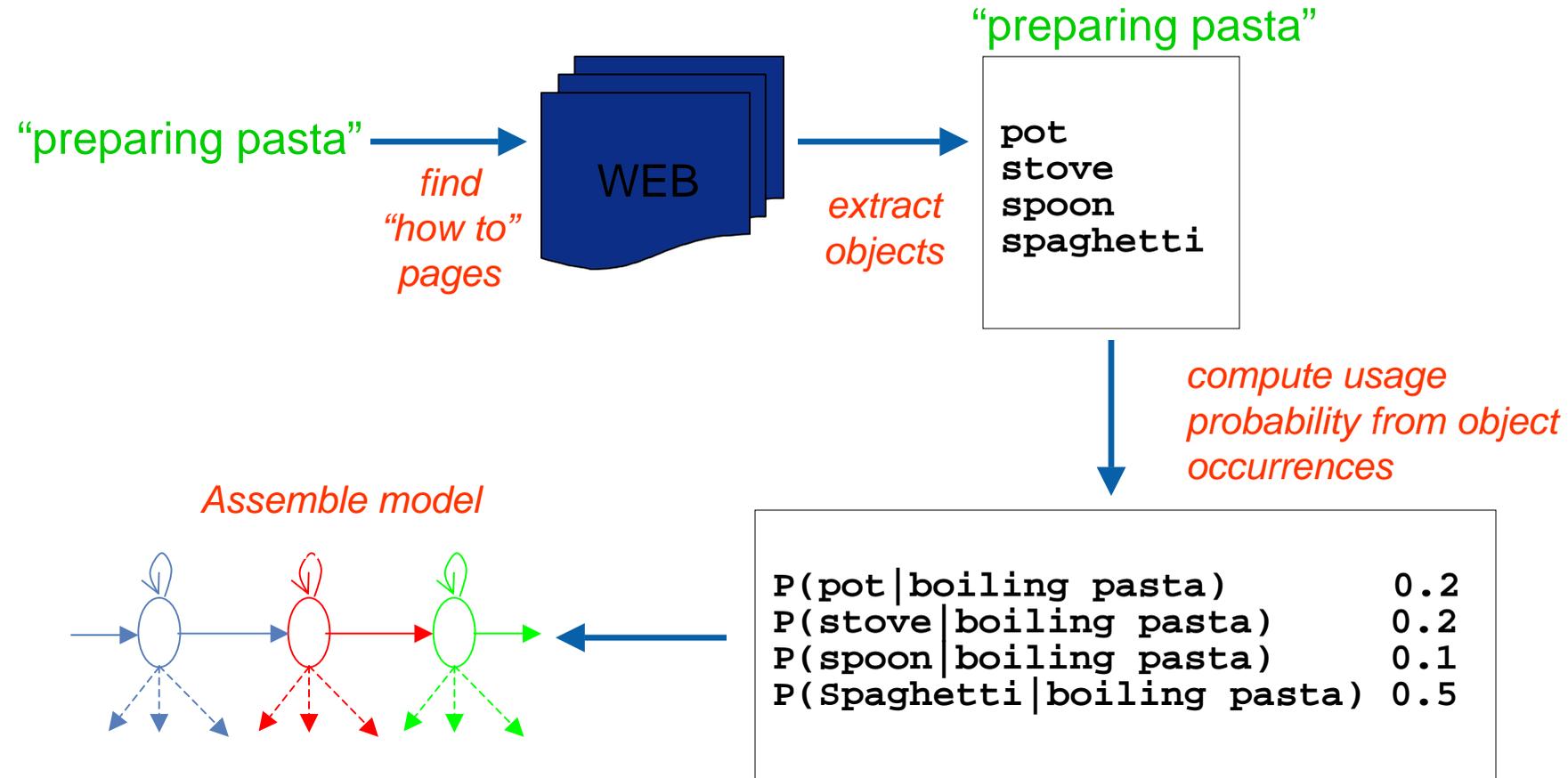
custom models



prepare pasta 20 times

# Techniques for constructing activity models: Mine activity from the web

(Wyatt et. al. AAI '05)



# Judging the level of independence of an elder

(1) inappropriate probabilities (2) Missing objects

Preparing pasta



pot



kitchen  
range



spaghetti



spoon

# Judging the level of independence of an elder

(1) inappropriate probabilities (2) Missing objects

## Preparing pasta



pot



kitchen  
range



spaghetti



spoon



pan



stove



macaroni



fork

# Dealing with Incompleteness

Exploit common sense information about objects that are functionally similar

pot → pan

spoon → fork

- automatically extract ontology from a hierarchically organized lexical system called WordNet

Adapt or improve model probabilities based on object similarity information

- apply statistical smoothing technique known as *shrinkage* to update model parameters



# WordNet: Semantic relationships

**Microwave#1:** electromagnetic wave

Synset: microwave

**Microwave#2:** kitchen appliance that cooks food

Synset: microwave, microwave oven



# WordNet: Semantic relationships

**Microwave#1:** electromagnetic wave

Synset: microwave

## Hypernym tree

Electromagnetic radiation

radiation

energy

Physical phenomenon

Natural phenomenon

Phenomenon

**Microwave#2:** kitchen appliance that cooks food

Synset: microwave, microwave oven

## Hypernym tree

Kitchen appliance

appliance

durables

Consumer goods

object

Entity

Hypernym: when a word sense is a superset of another



# WordNet: Semantic relationships

How do we select the word sense automatically?

## Hypernym tree

Electromagnetic radiation

radiation

energy

Physical phenomenon

Natural phenomenon

Phenomenon

## Hypernym tree

Kitchen appliance

appliance

durables

Consumer goods

object

Entity



# WordNet: Unique beginners for nouns

*Thing, entity*

*Non-living thing, object*

*Living thing, organism*

• *Natural object*

• *Artifact*

• *Substance*

• *food*

• *Plant, flora*

• *Animal, fauna*

• *Person, human  
being*



# WordNet: Semantic relationships

How do we select the word sense automatically?

## Hypernym tree

Electromagnetic radiation

radiation

energy

Physical phenomenon

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Phenomenon

## Hypernym tree

Kitchen appliance

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Consumer goods

object

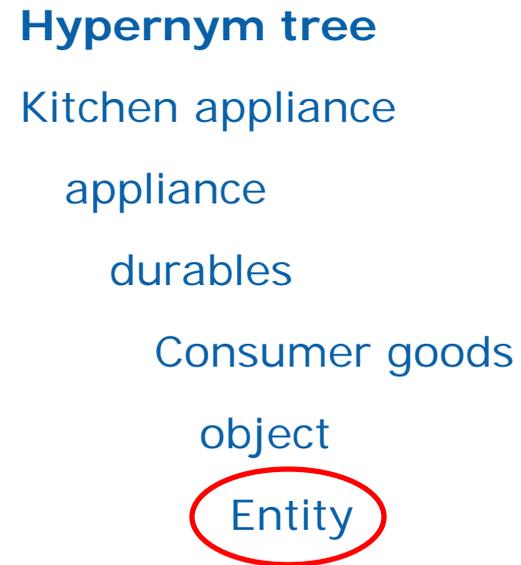
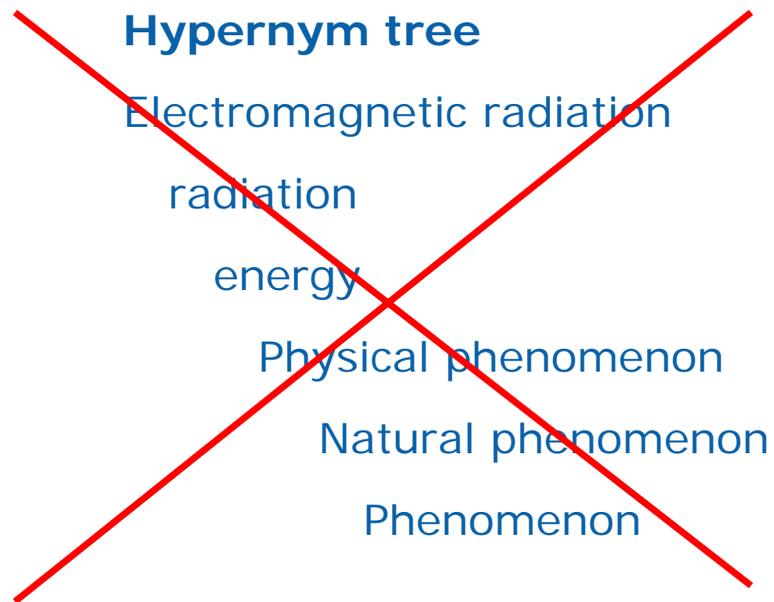
Entity

Identify objects that are (1) nouns (2) subset of entity



# WordNet: Semantic relationships

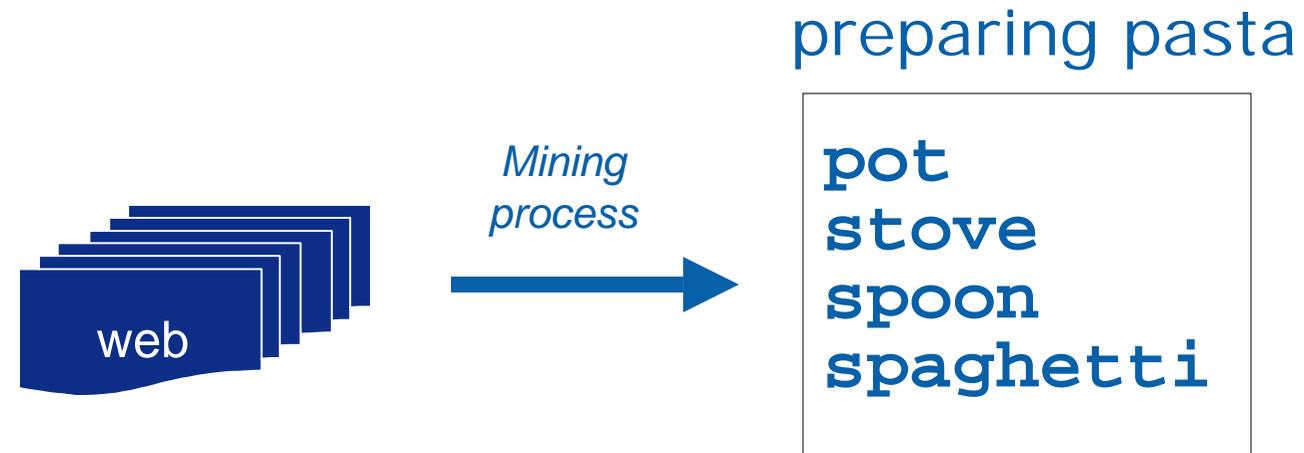
How do we select the word sense automatically?



Identify objects that are (1) nouns (2) subset of entity

# Ontology extraction from WordNet

From the activity recipe mined for “preparing pasta”, we have the list of objects used.



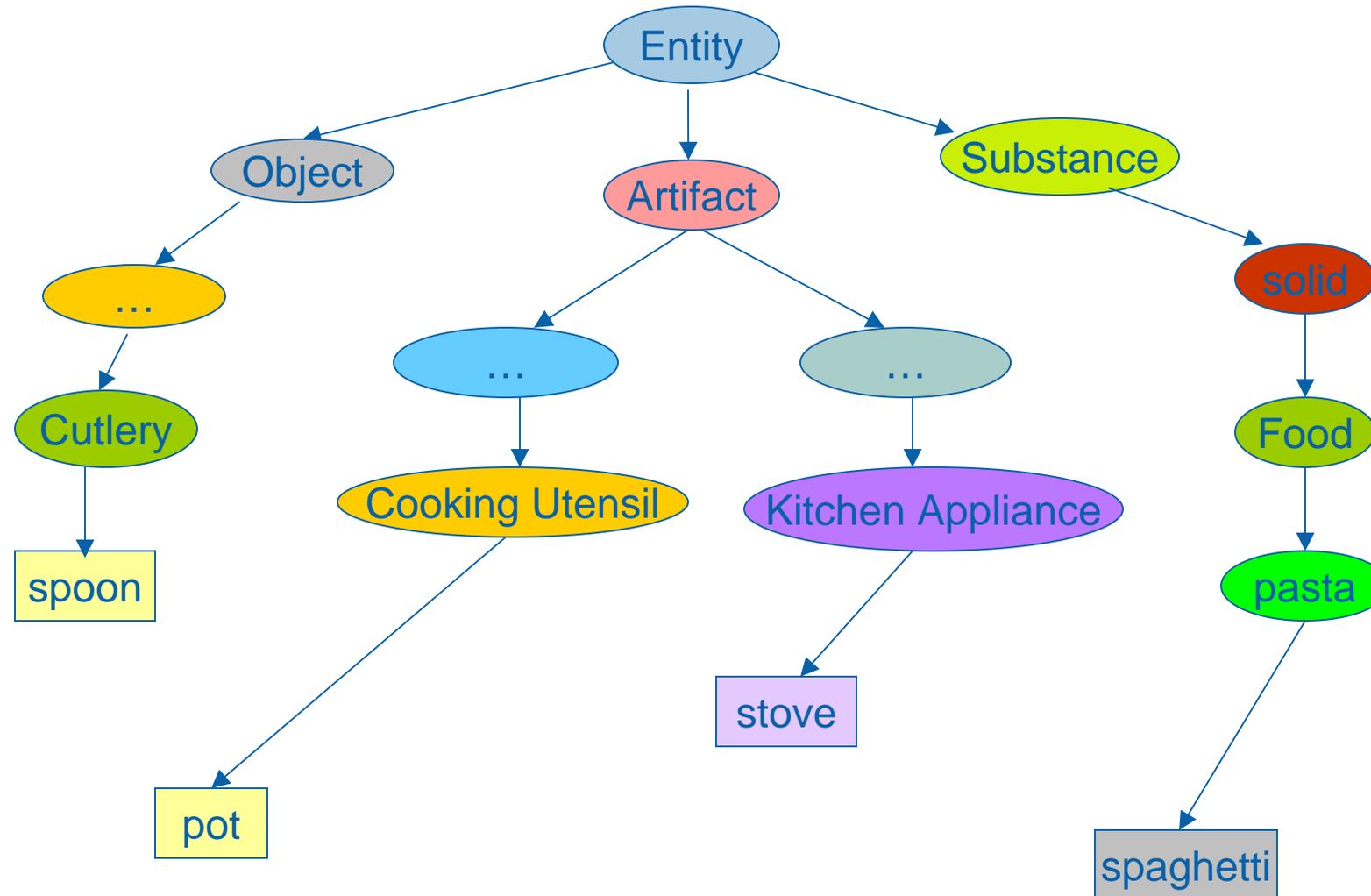
# Ontology extraction from WordNet

Finding the first hypernym tree that contain the concept entity for all the objects in our list we get

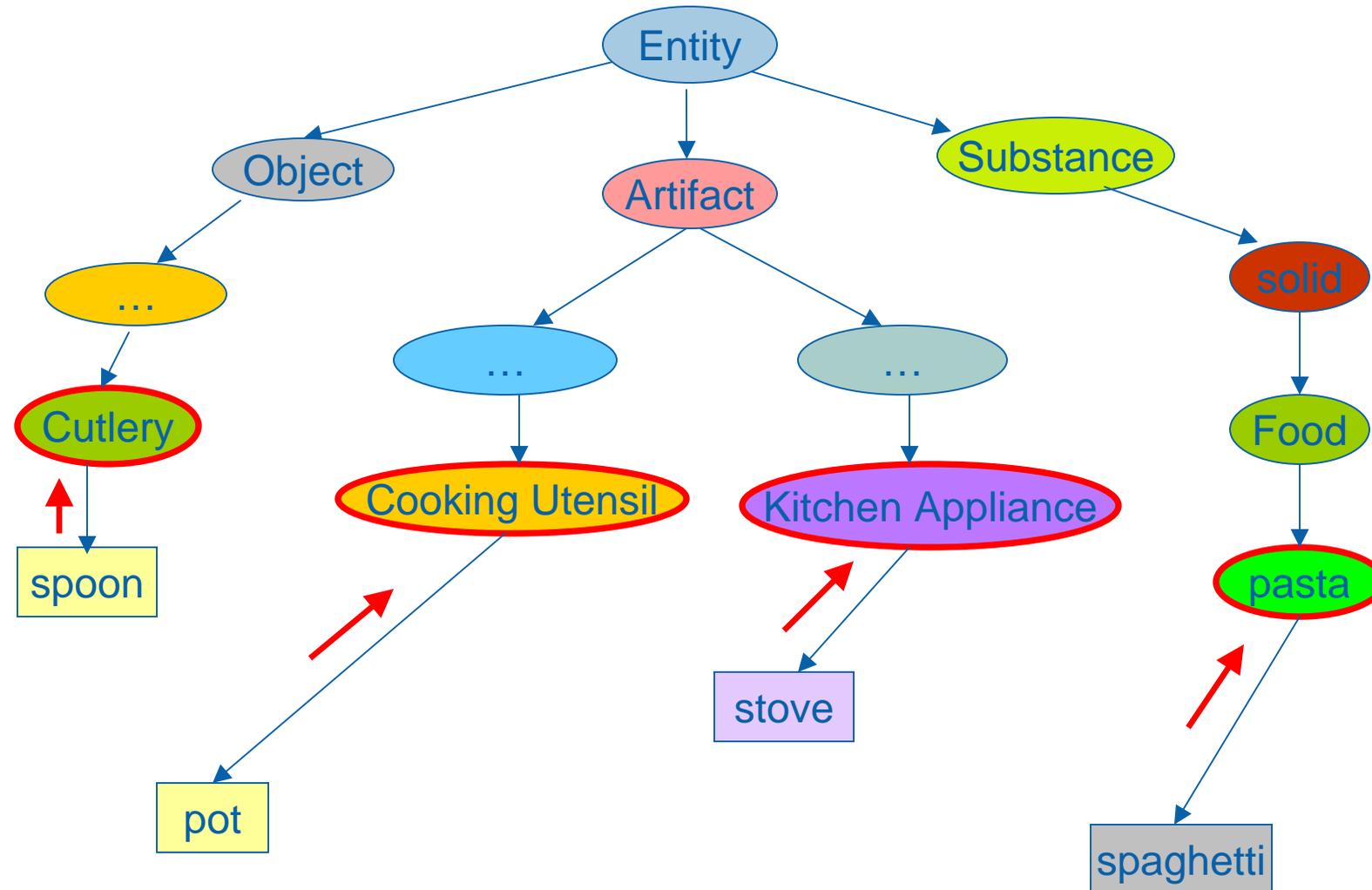
<b>pot</b>	<b>stove</b>	<b>spoon</b>	<b>pasta</b>
Cooking utensil	kitchen appliance	cutlery	food
Utensil	home appliance	tableware	solid
Implement	appliance	ware	substance
Instrumentality	durables	article	entity
Artifact	consumer goods	artifact	
Entity	commodity	object	
	artifact	entity	
	entity		



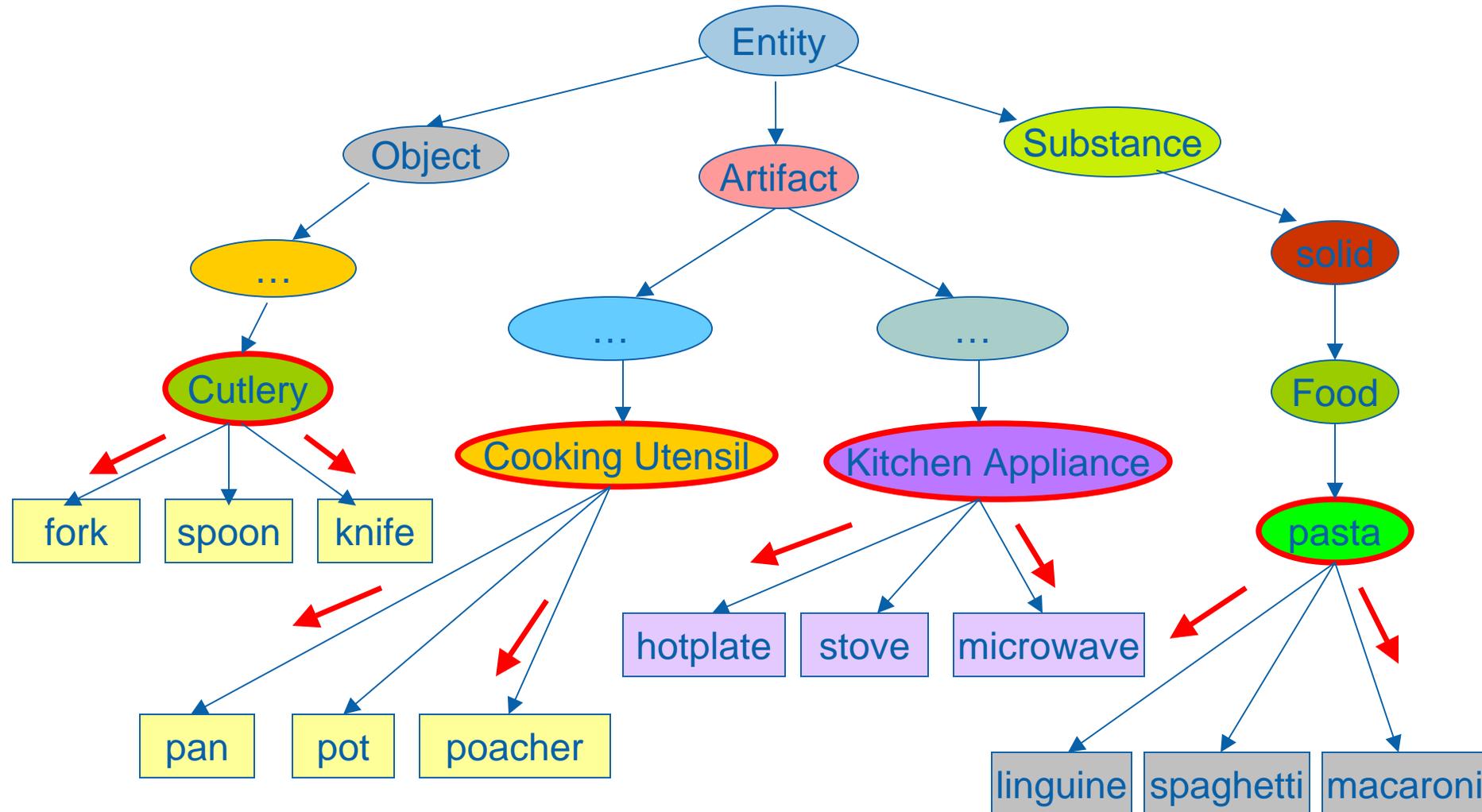
# WordNet ontology generation



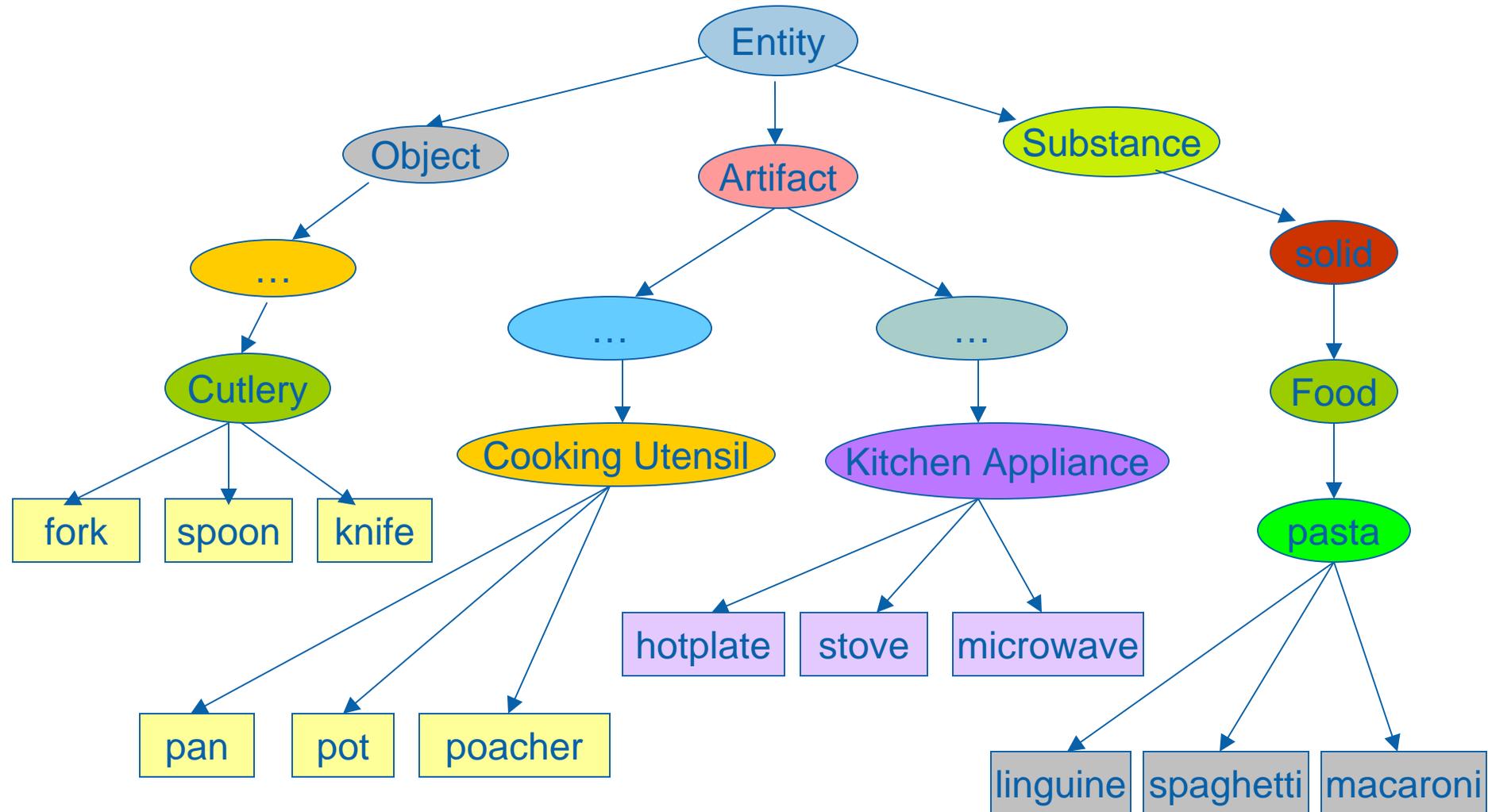
# WordNet ontology expansion



# WordNet ontology expansion



# WordNet ontology



# Ontology extraction from WordNet

From the activity recipe mined for “preparing pasta”, we also have the probabilities of object use

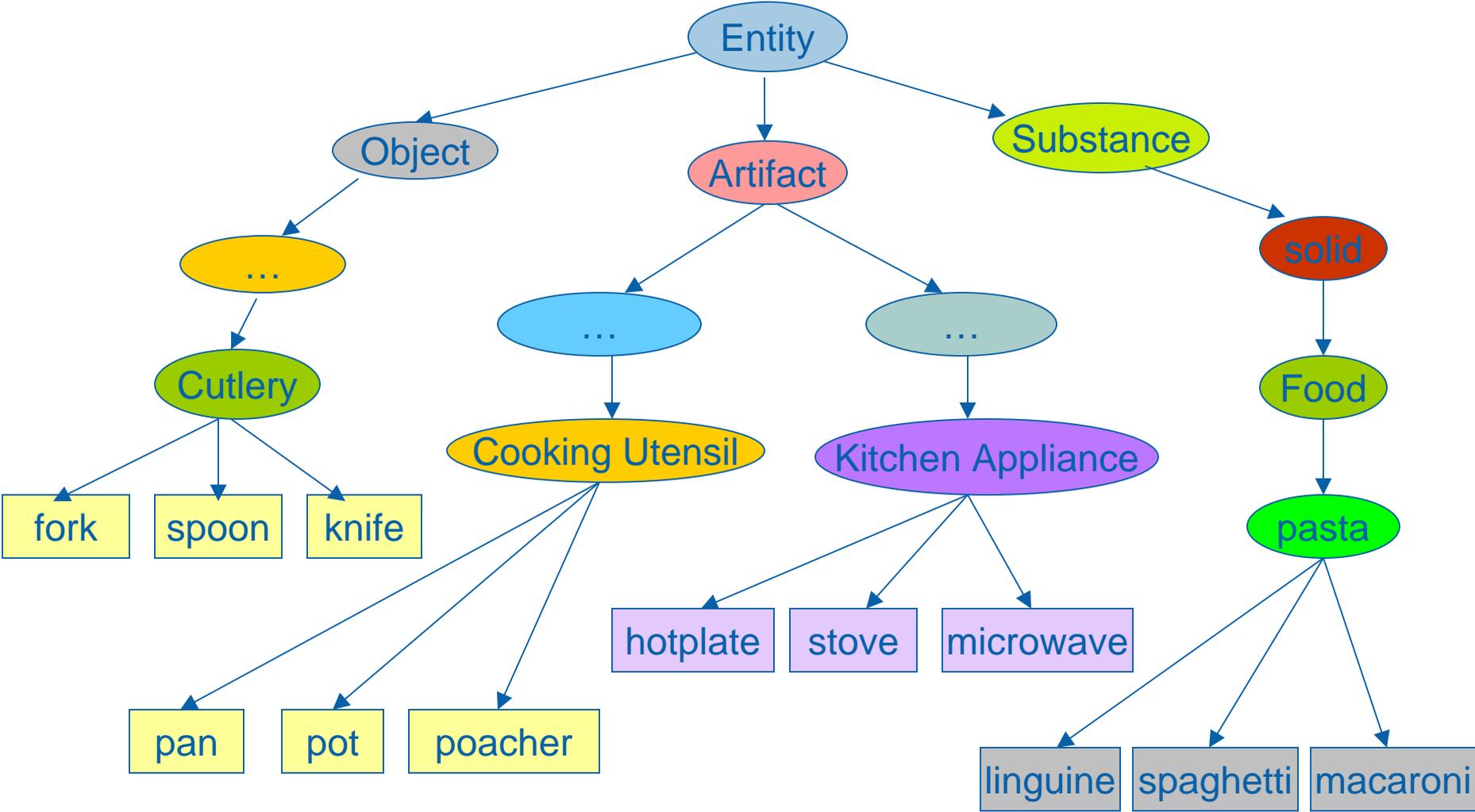
preparing pasta

pot  
stove  
spoon  
Spaghetti

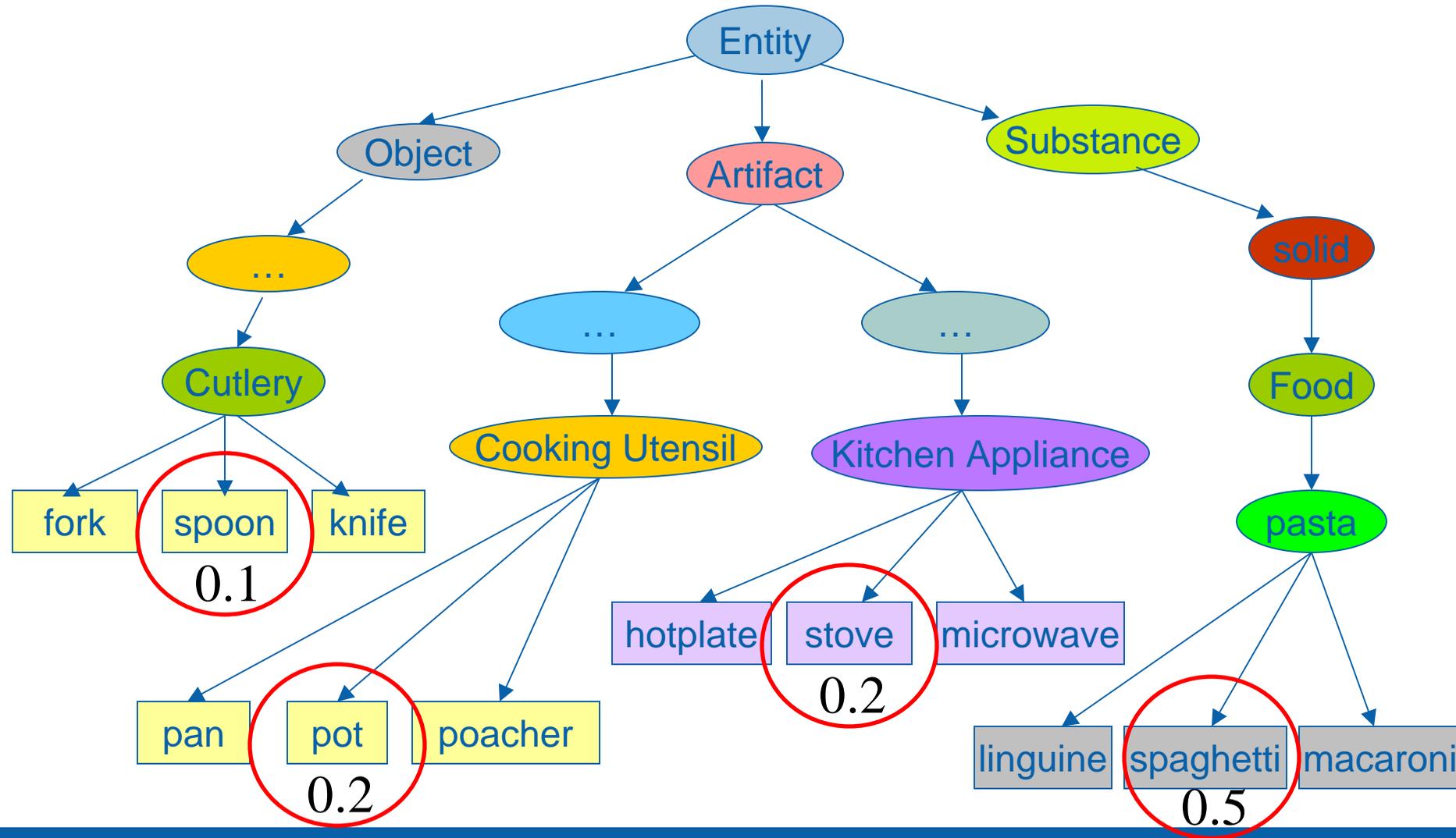
P(pot preparing pasta)	0.2
P(stove preparing pasta)	0.2
P(spoon preparing pasta)	0.1
P(Spaghetti preparing pasta)	0.5



# Ontology: setting probabilities



# Ontology: setting probabilities



# What if we use macaroni instead?

## Preparing pasta



pot



kitchen  
range



spaghetti



spoon



pan



stove

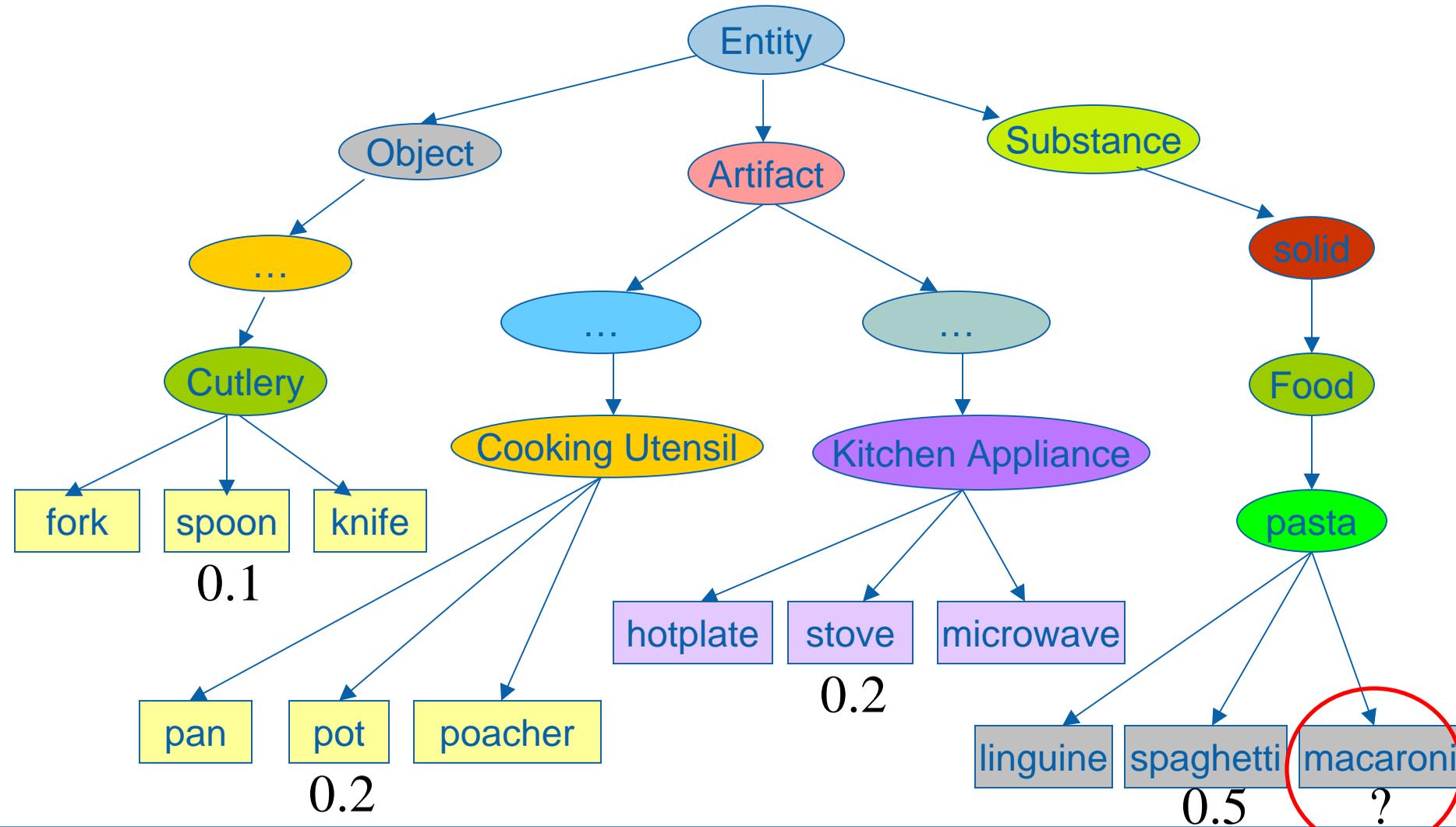


macaroni

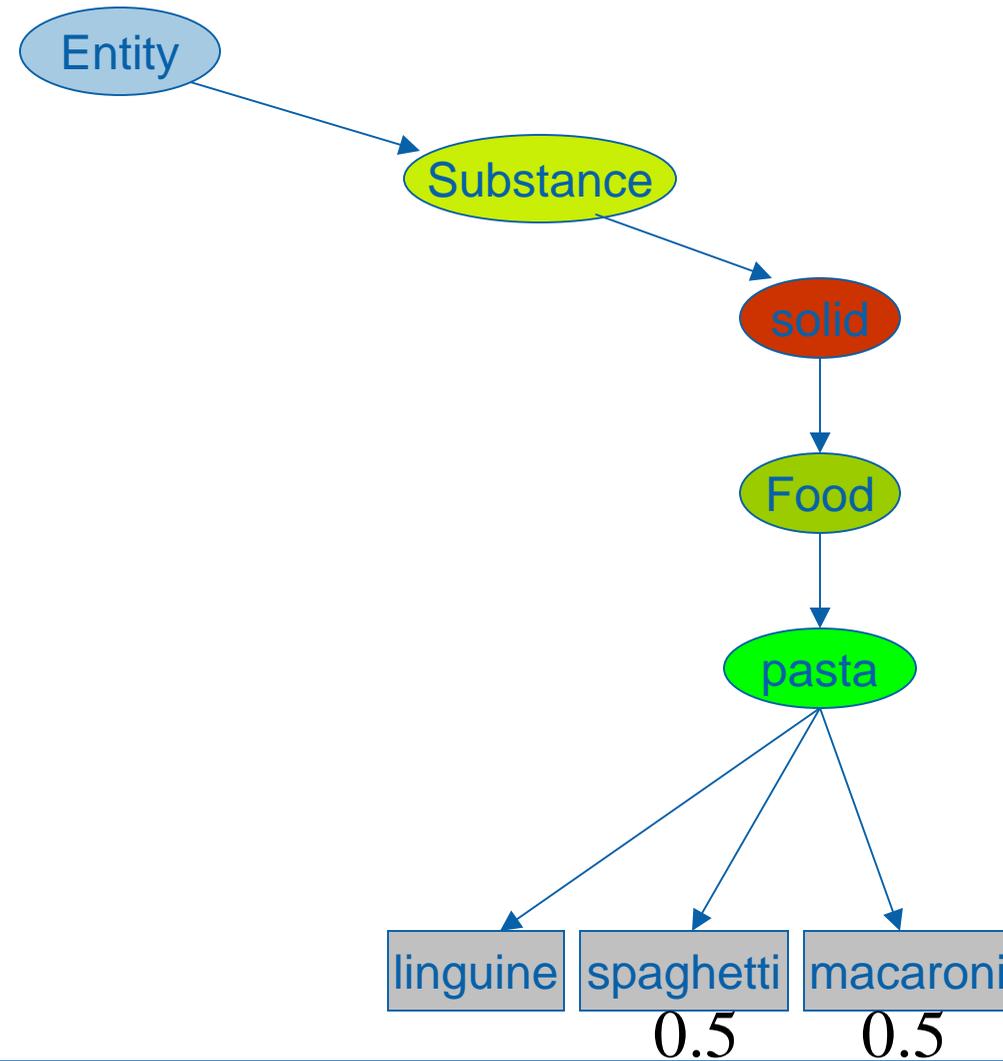


fork

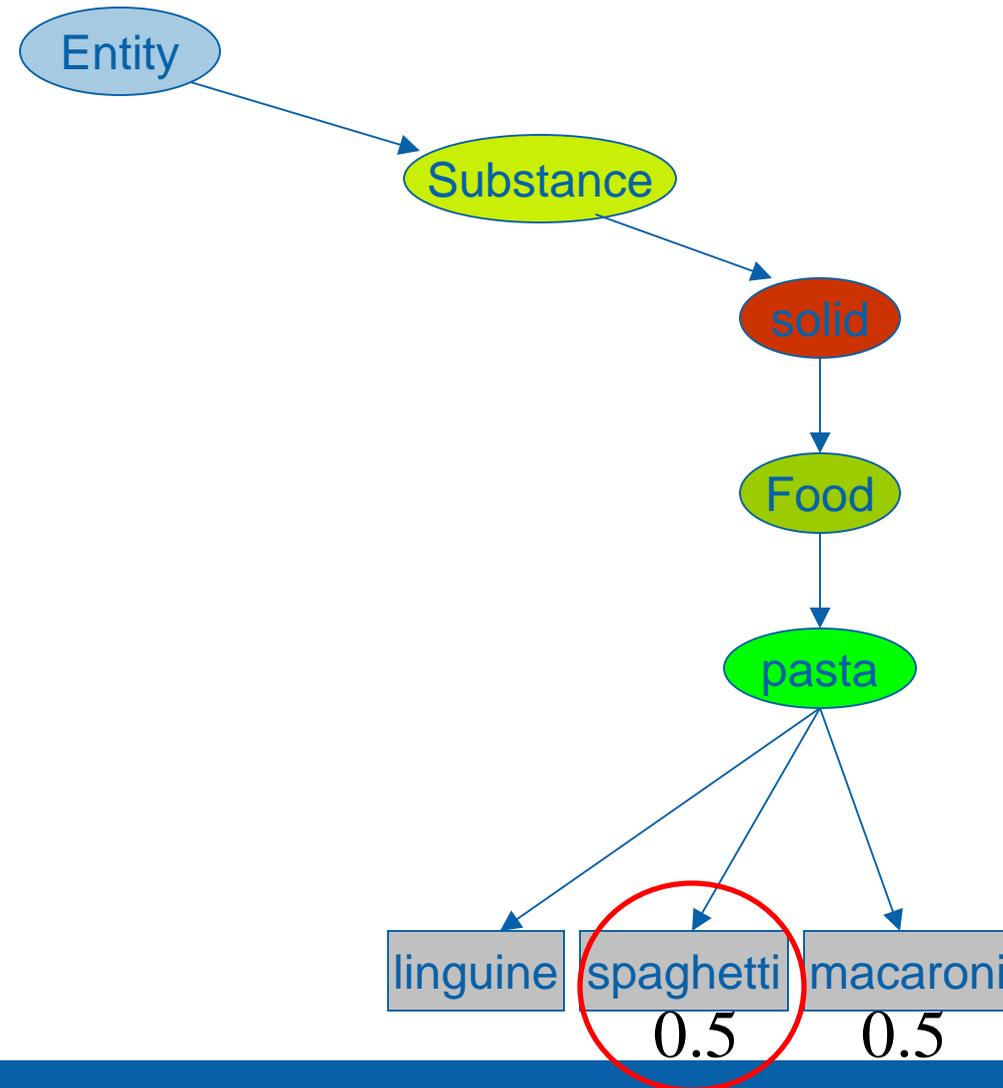
# How do we propagate probabilities?



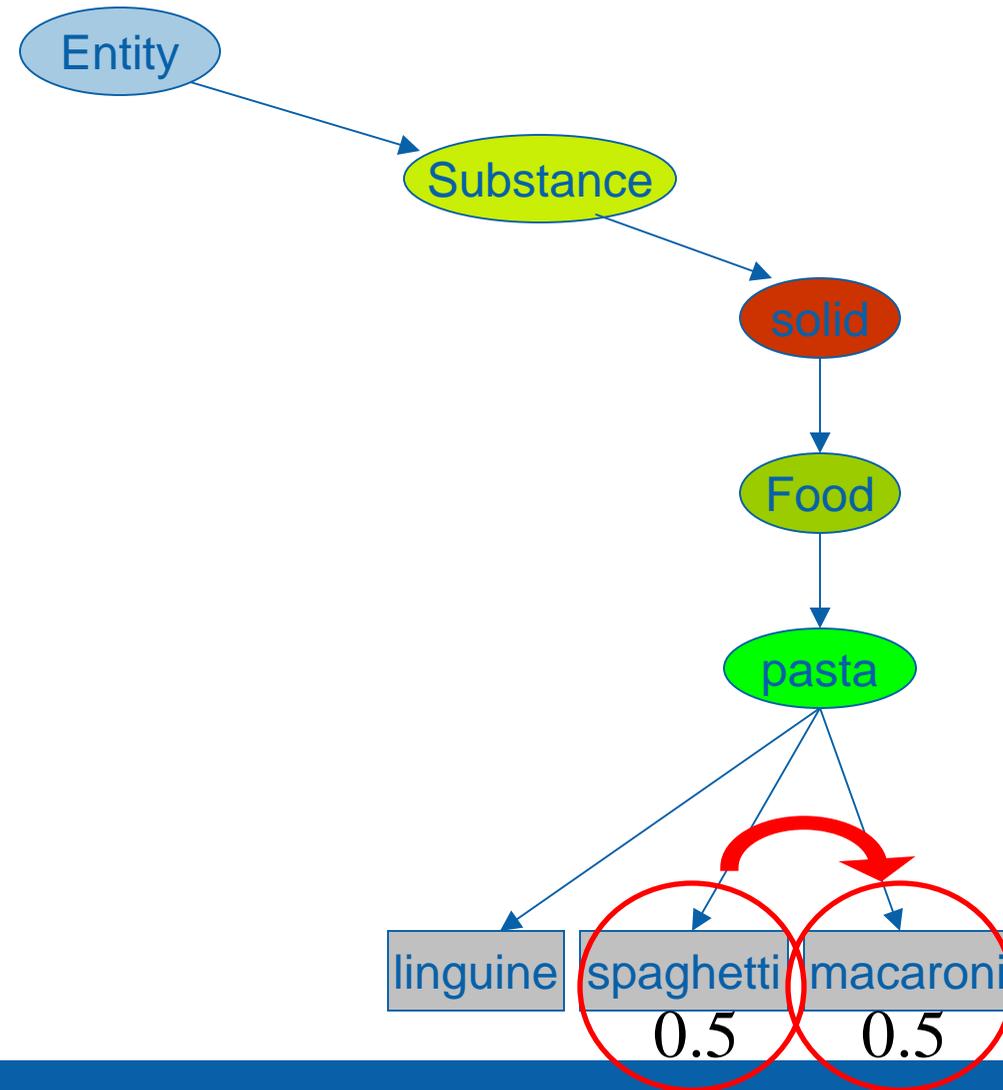
# Copy probability from sibling node to sibling node



# Copy probability from sibling node to sibling node

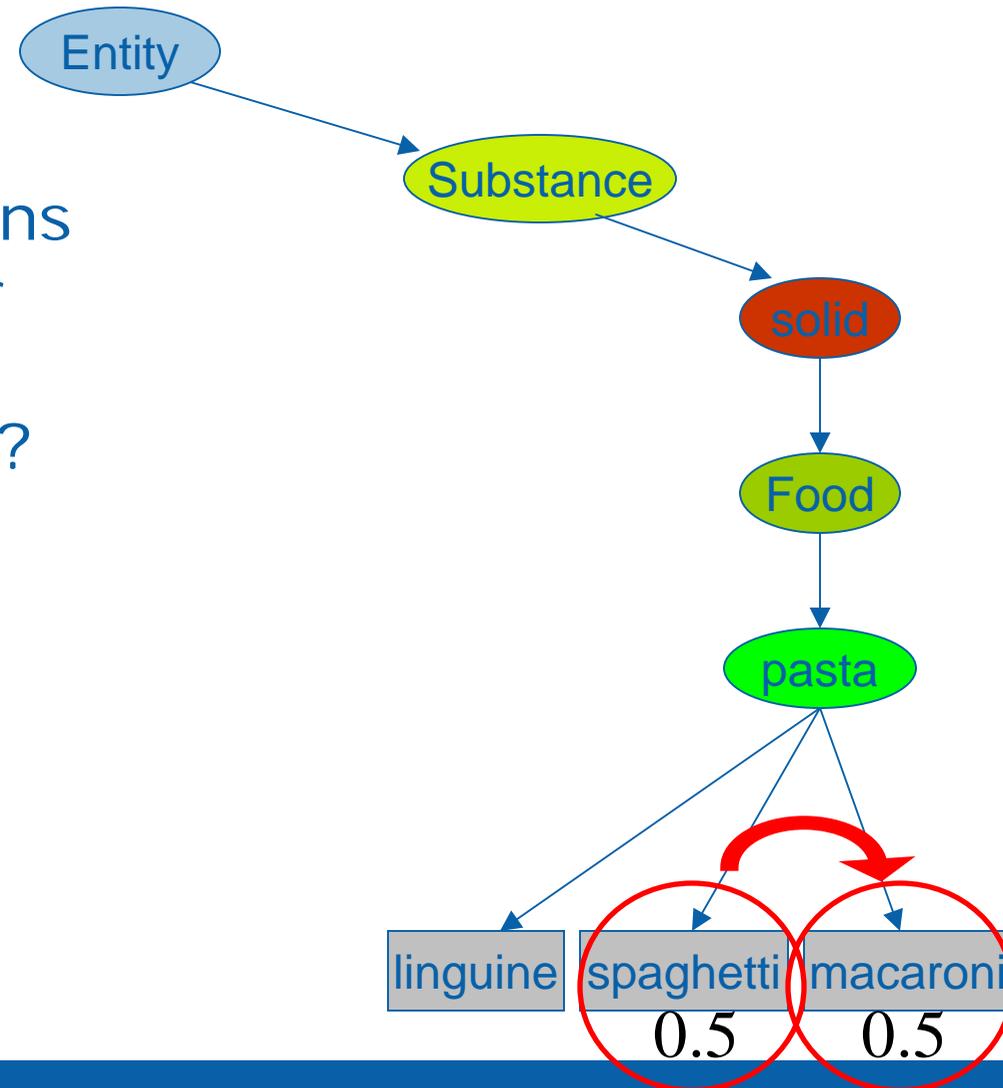


# Copy probability from sibling node to sibling node



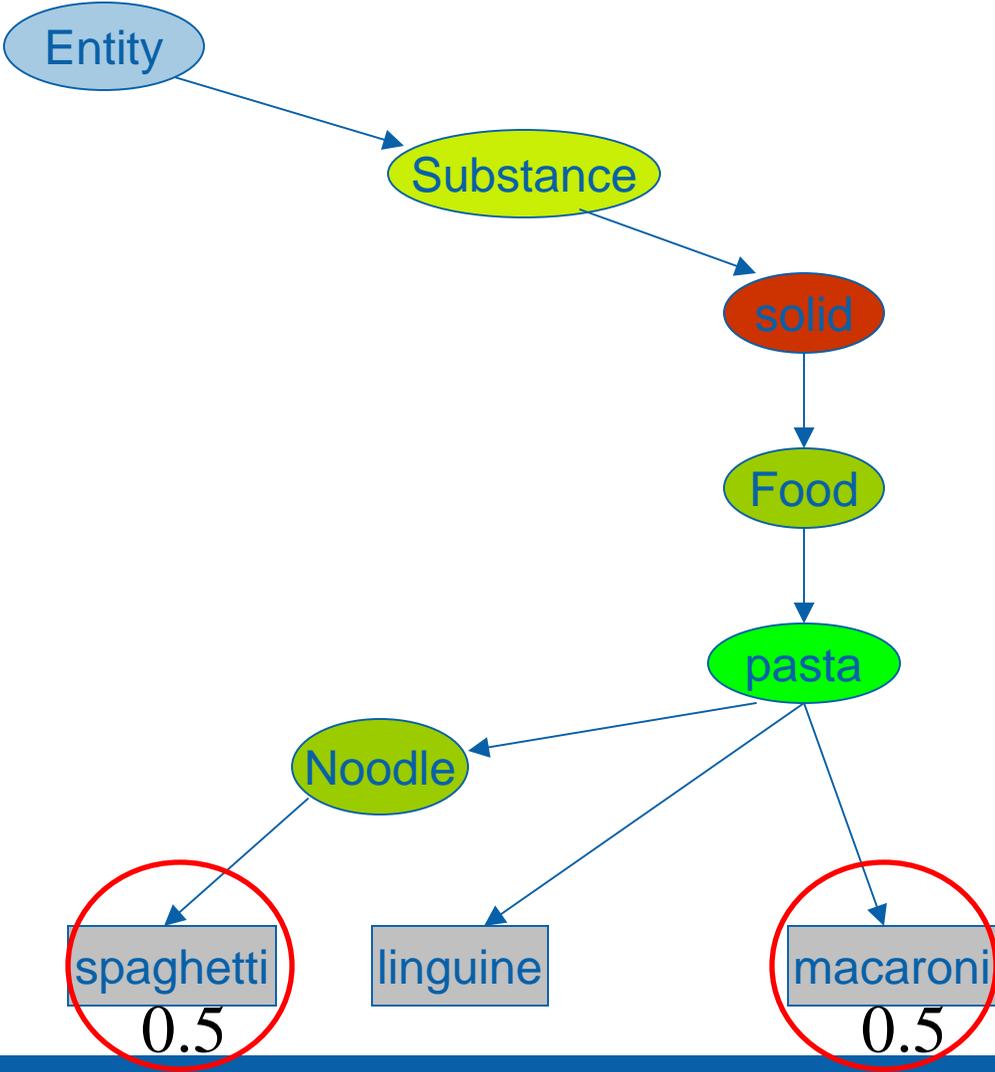
# Copy probability from sibling node to sibling node

Problem: What happens if the probability for spaghetti is inappropriate or bad?



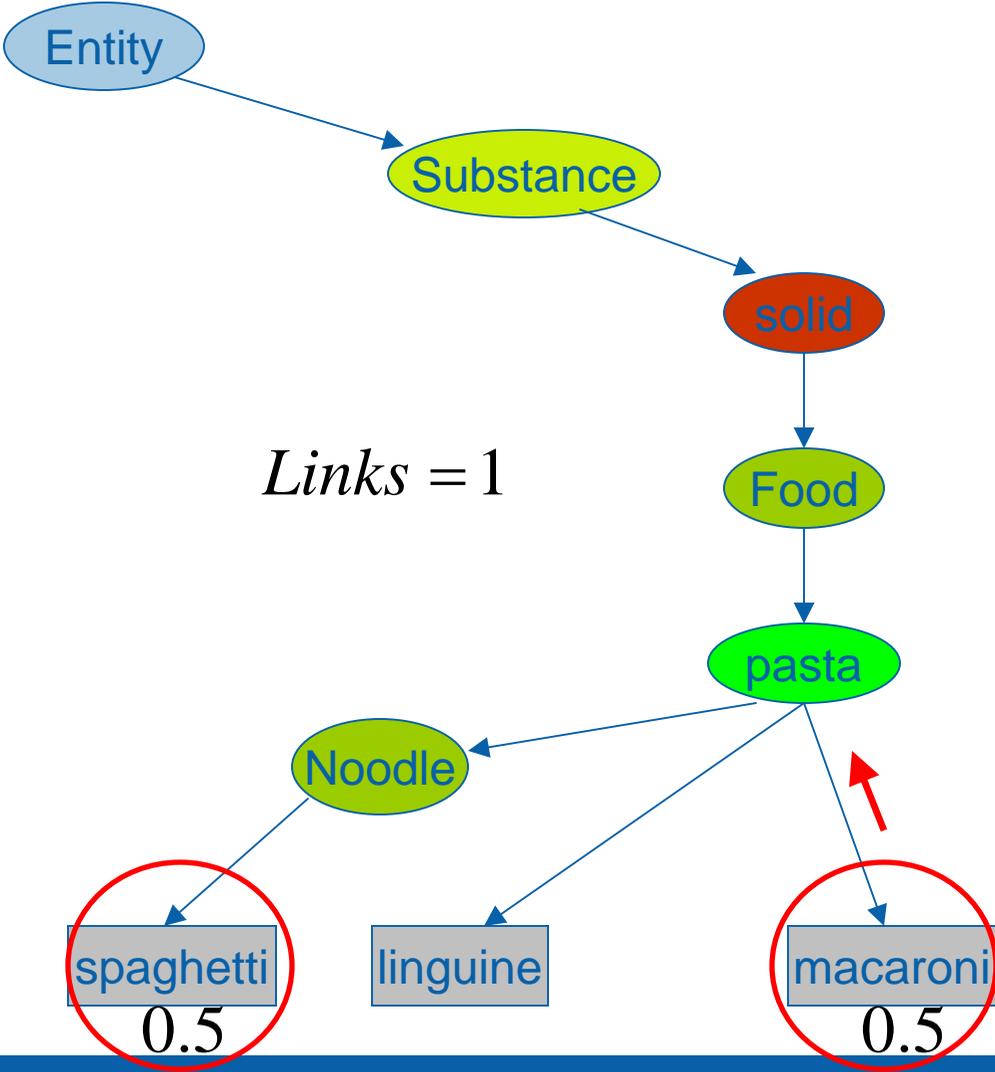
# Count number of links from node to node

Problem: What happens if spaghetti is not an immediate sibling of macaroni?



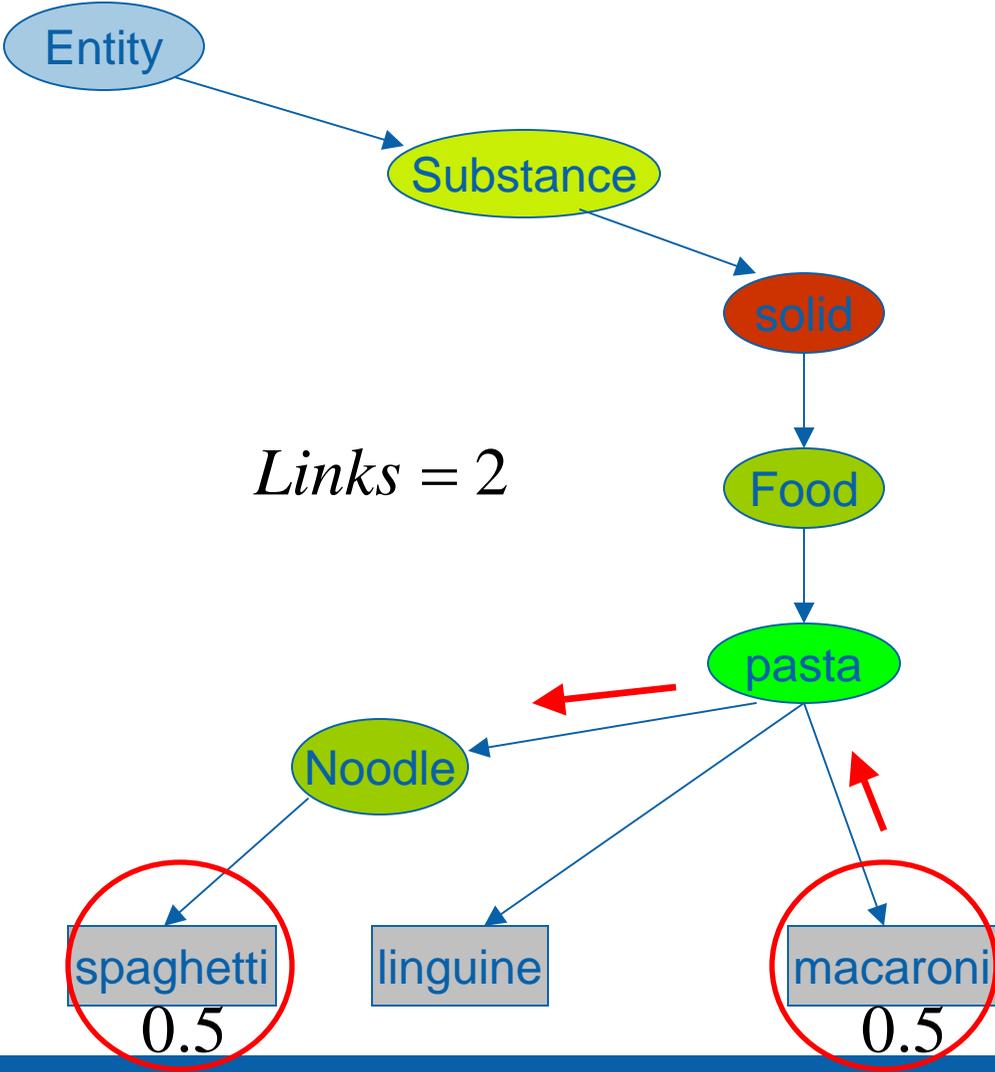
# Count number of links from node to node

Problem: What happens if spaghetti is not an immediate sibling of macaroni?



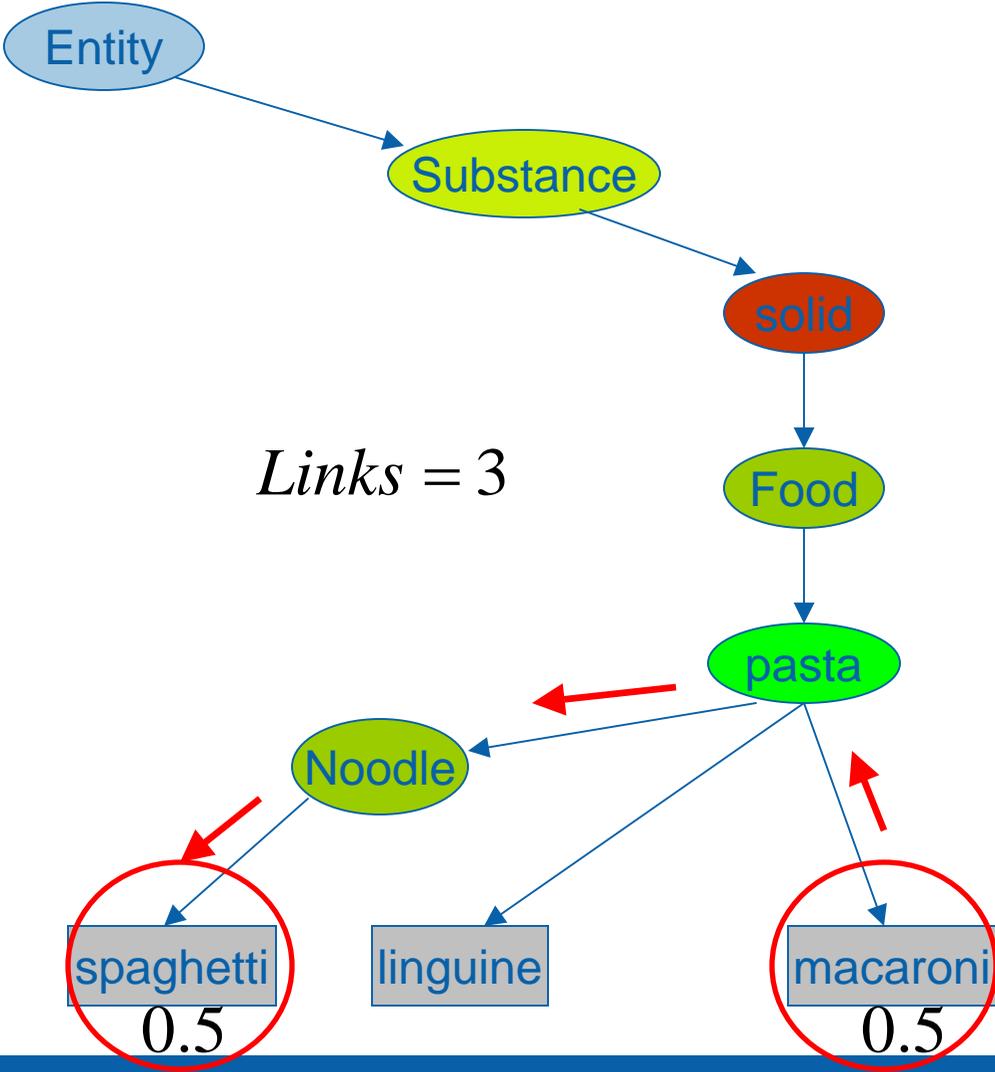
# Count number of links from node to node

Problem: What happens if spaghetti is not an immediate sibling of macaroni?



# Count number of links from node to node

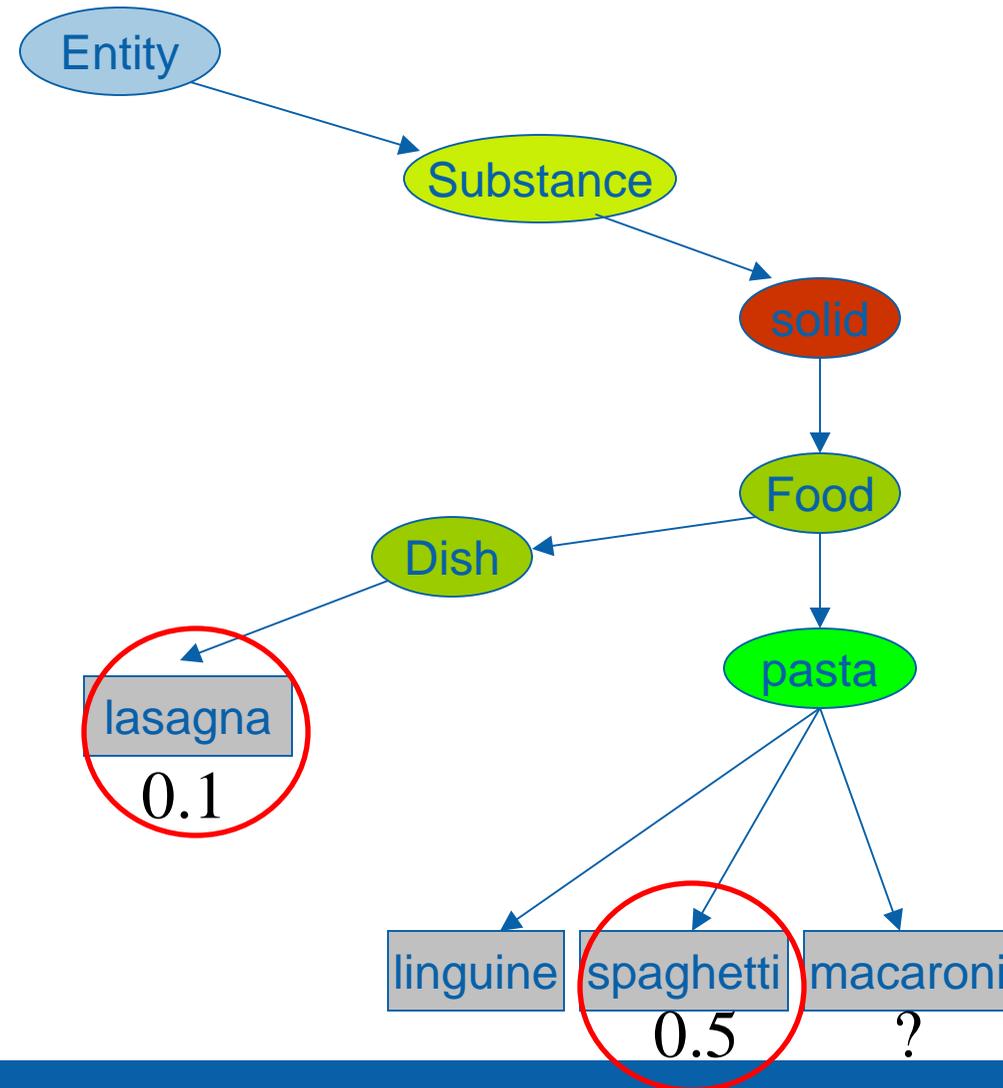
Problem: What happens if spaghetti is not an immediate sibling of macaroni?



# Taking additional information into account

What happens if we also know that somebody preparing pasta can use lasagna?

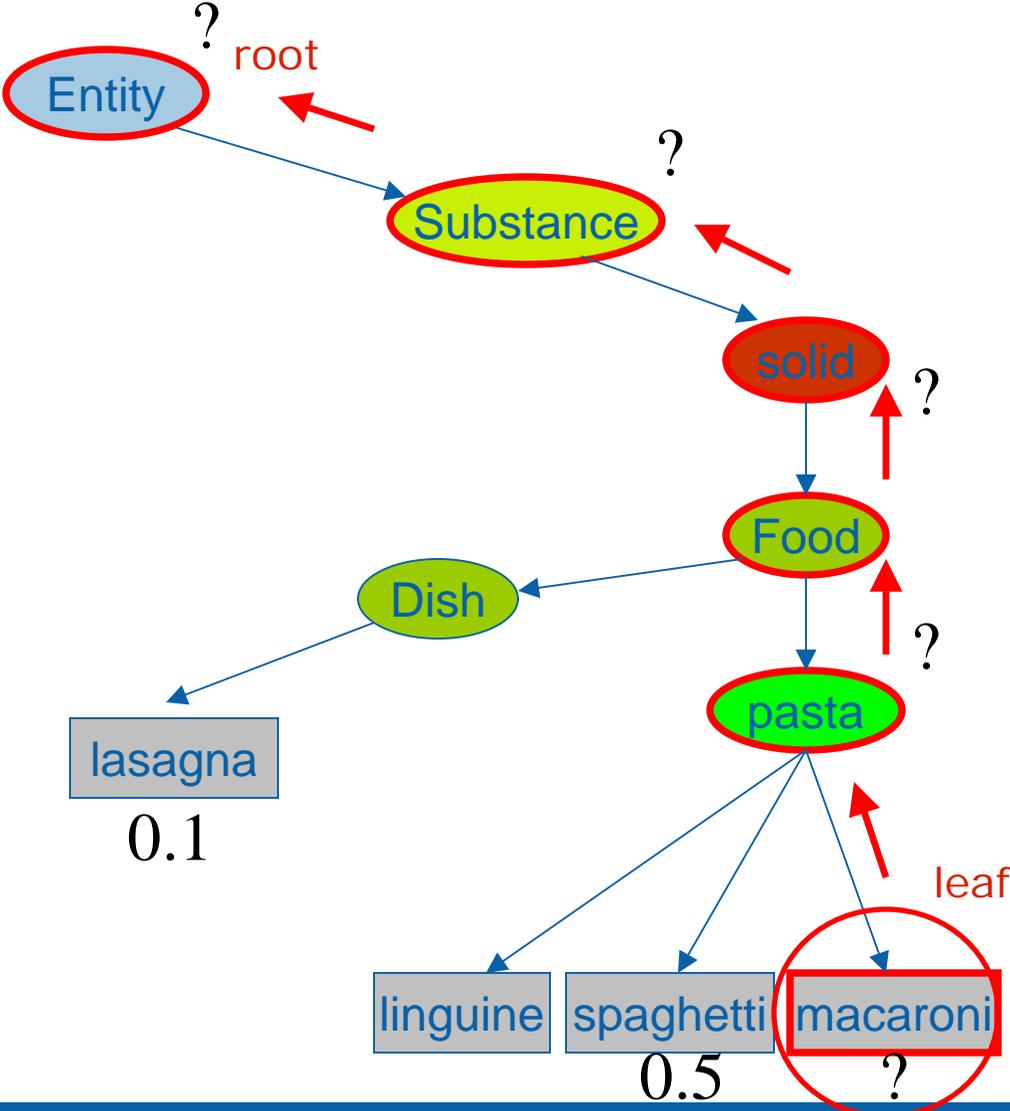
None of the two previous techniques can take advantage of this extra information



# Shrinkage: Key idea

Idea: find or improve the parameter estimate of leaf nodes by linearly interpolating the estimates of its ancestor nodes

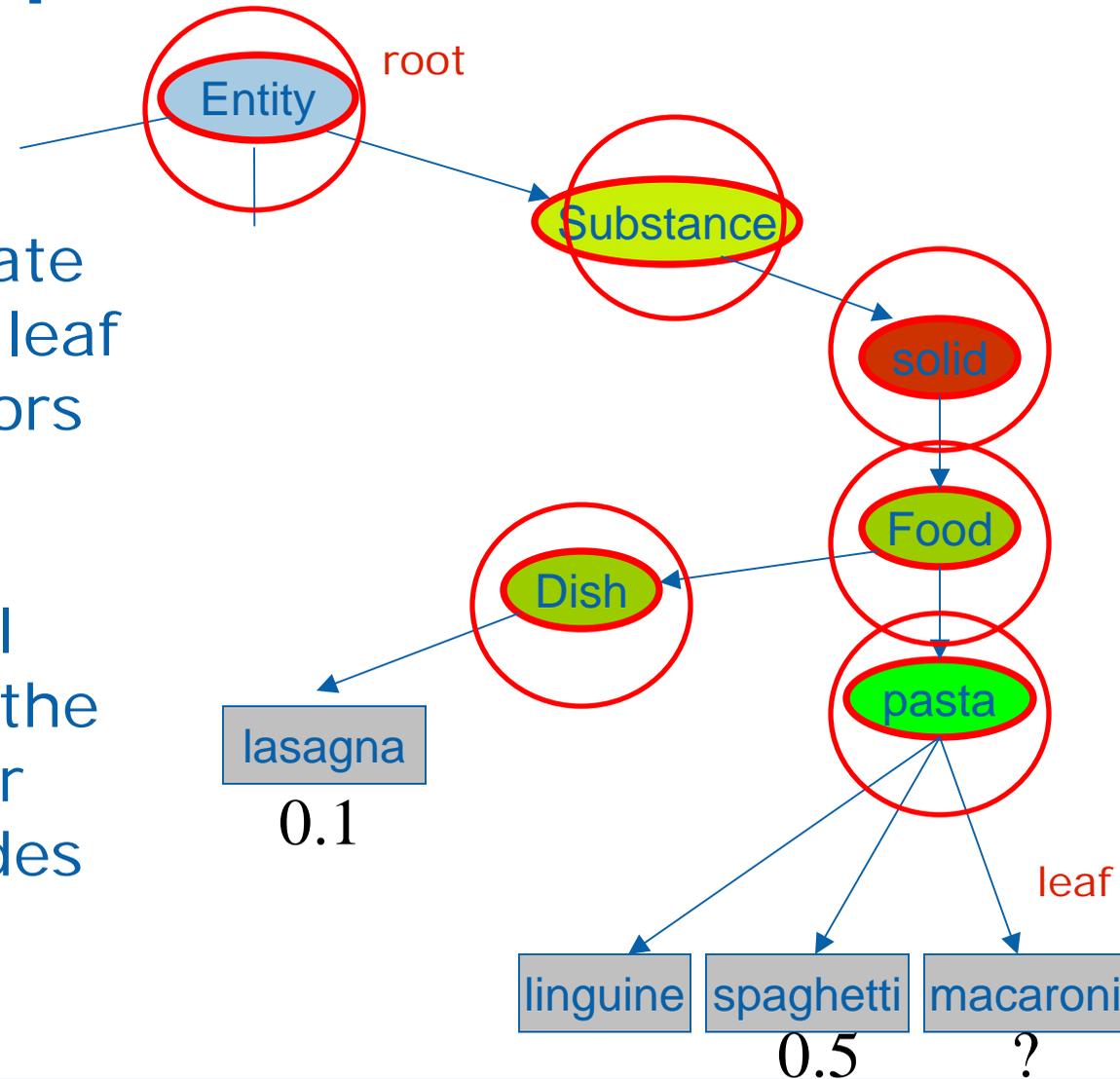
How do we compute estimates for internal nodes?



# Shrinkage: Step two

Answer: Propagate information from leaf nodes to ancestors

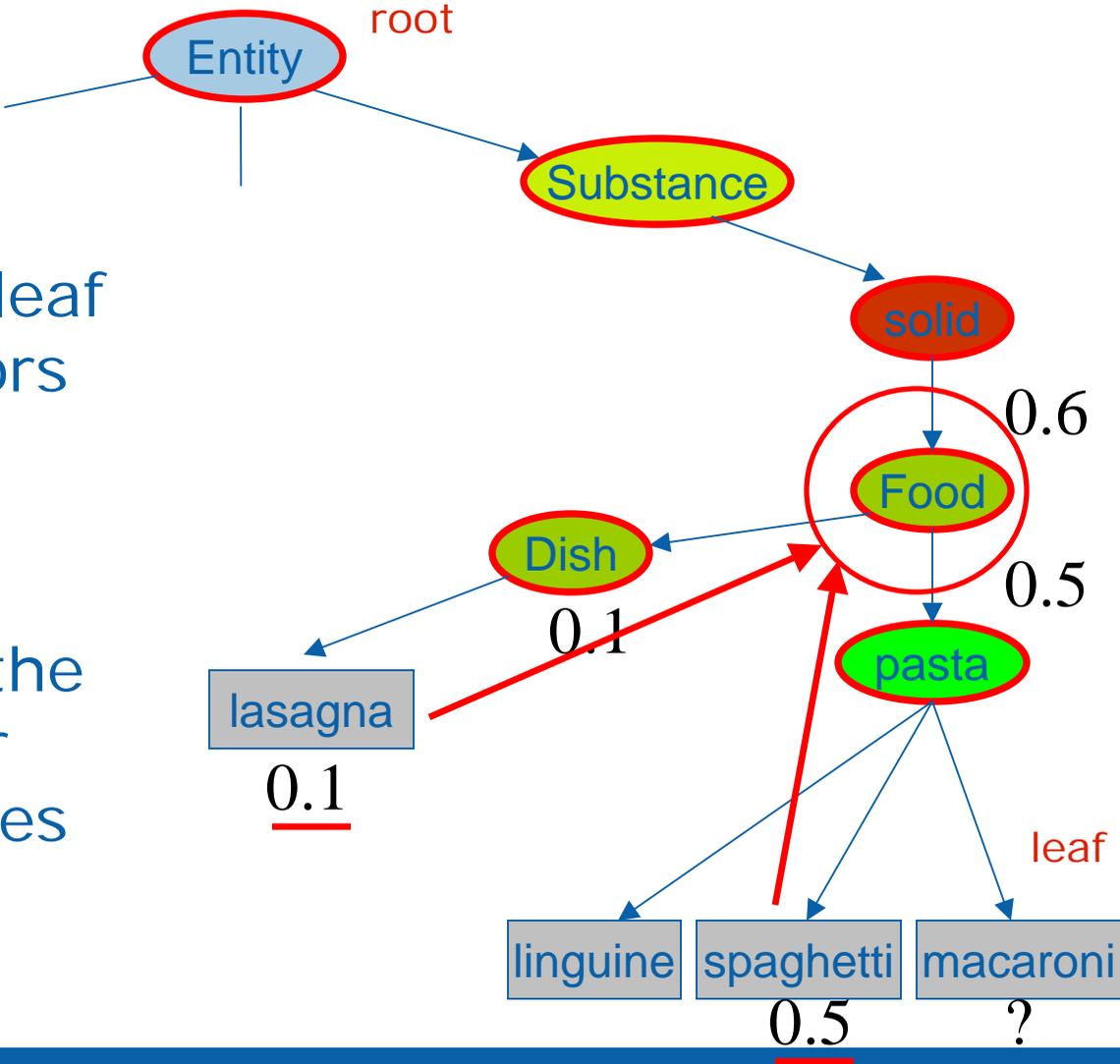
For all internal nodes, compute the sum of all their children leaf nodes



# Shrinkage: Step two

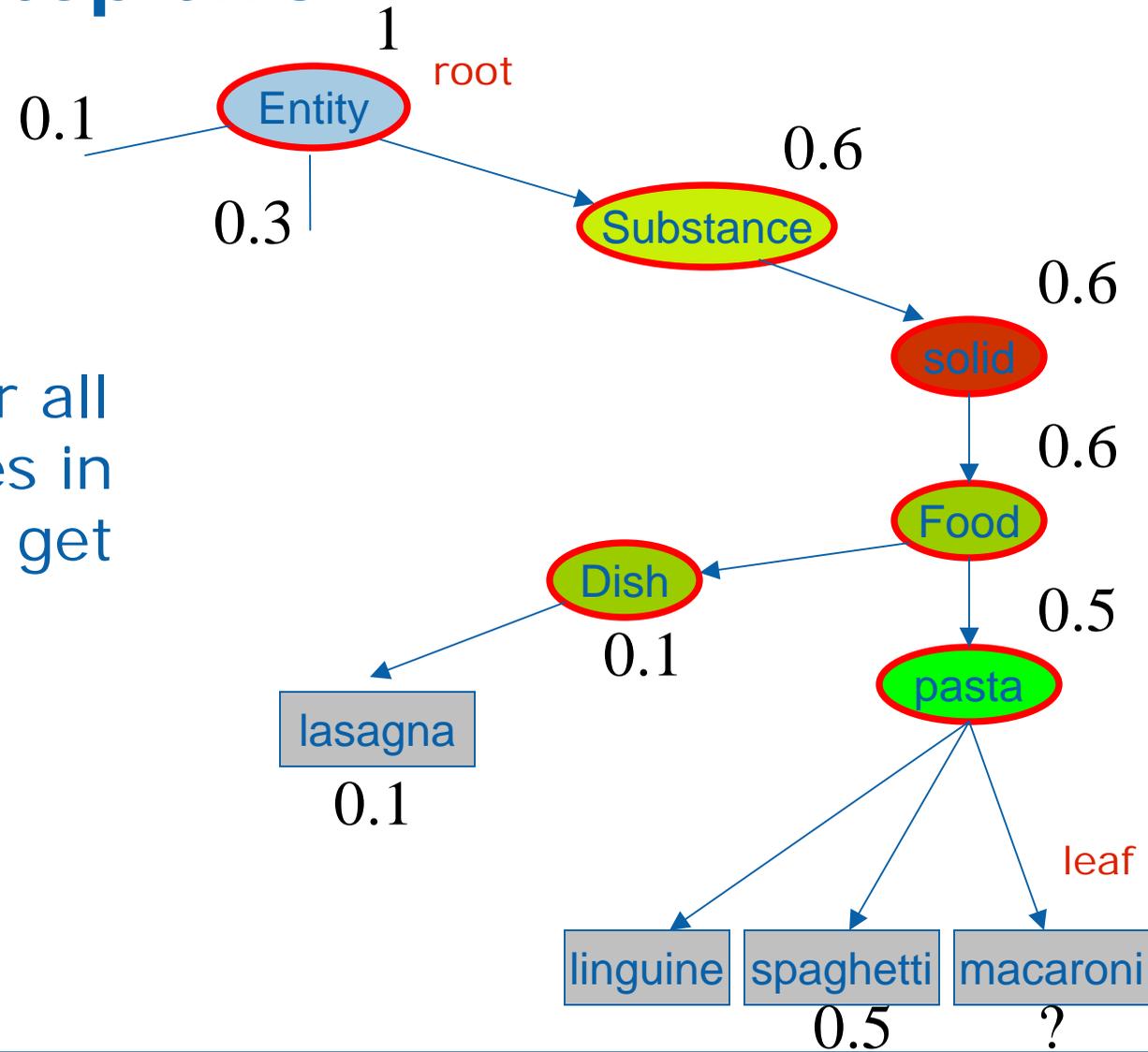
Propagate information from leaf nodes to ancestors

For all internal nodes, compute the sum of all their children leaf nodes



# Shrinkage: Step two

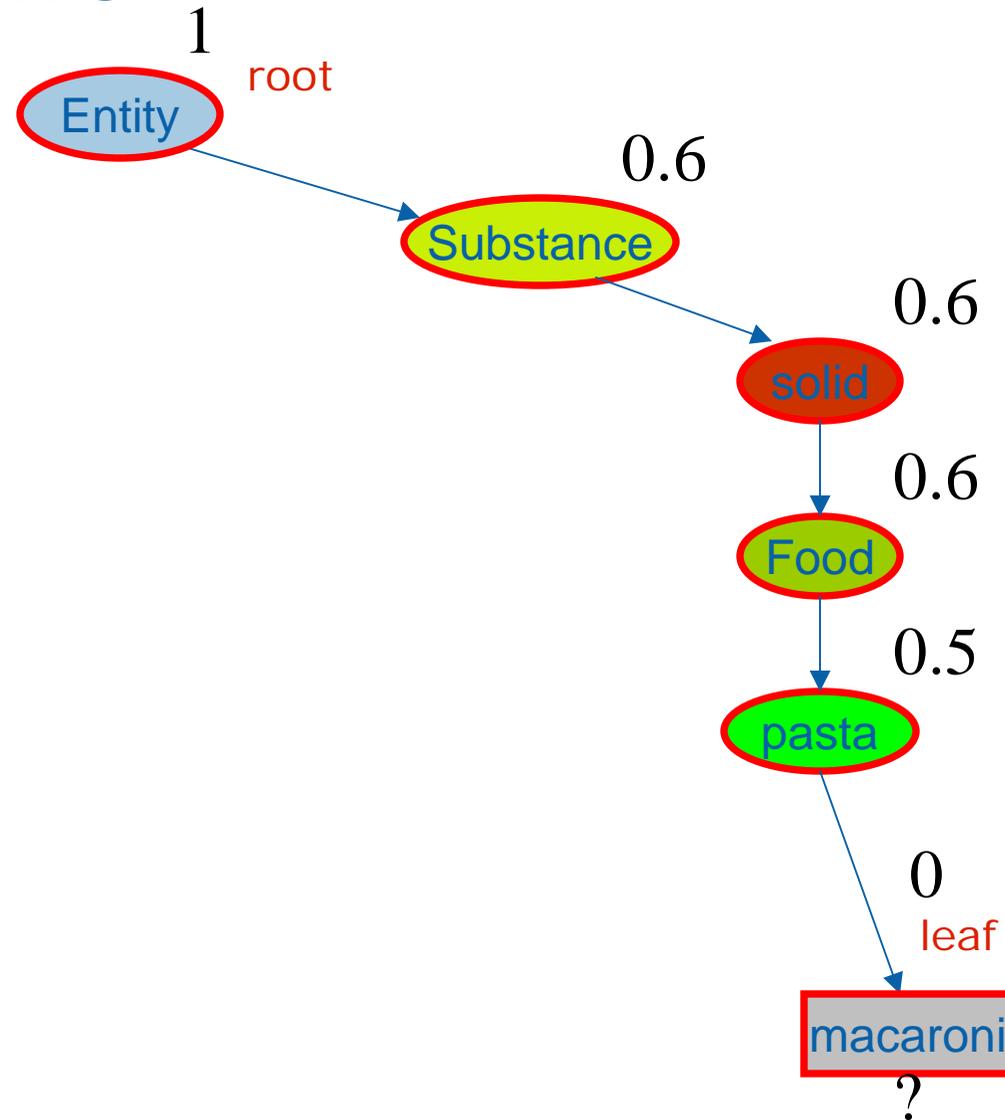
Repeating for all internal nodes in ontology, we get



# Shrinkage: Step two

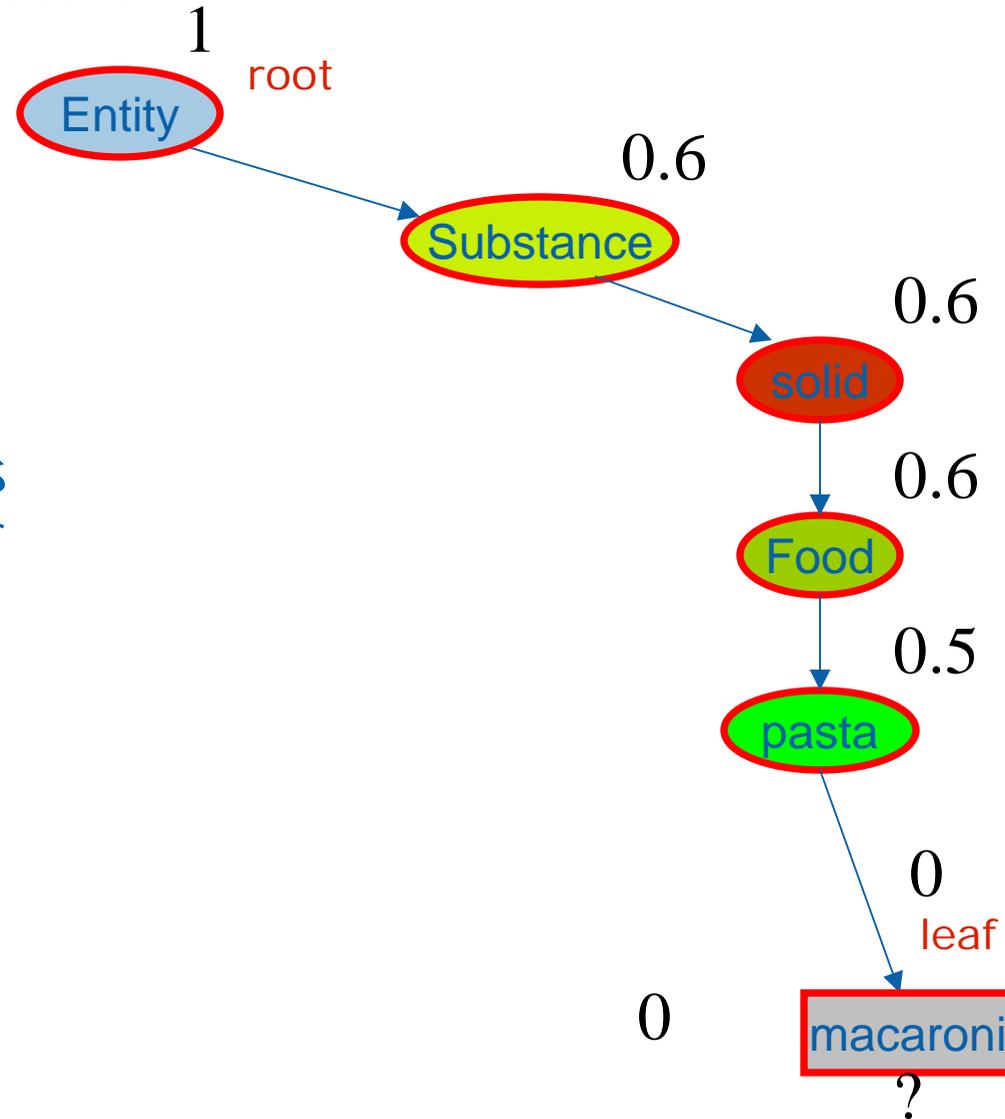
Now, we just focus on the nodes from the leaf to the root

$$\tilde{p}(\textit{macaroni}) = ?$$



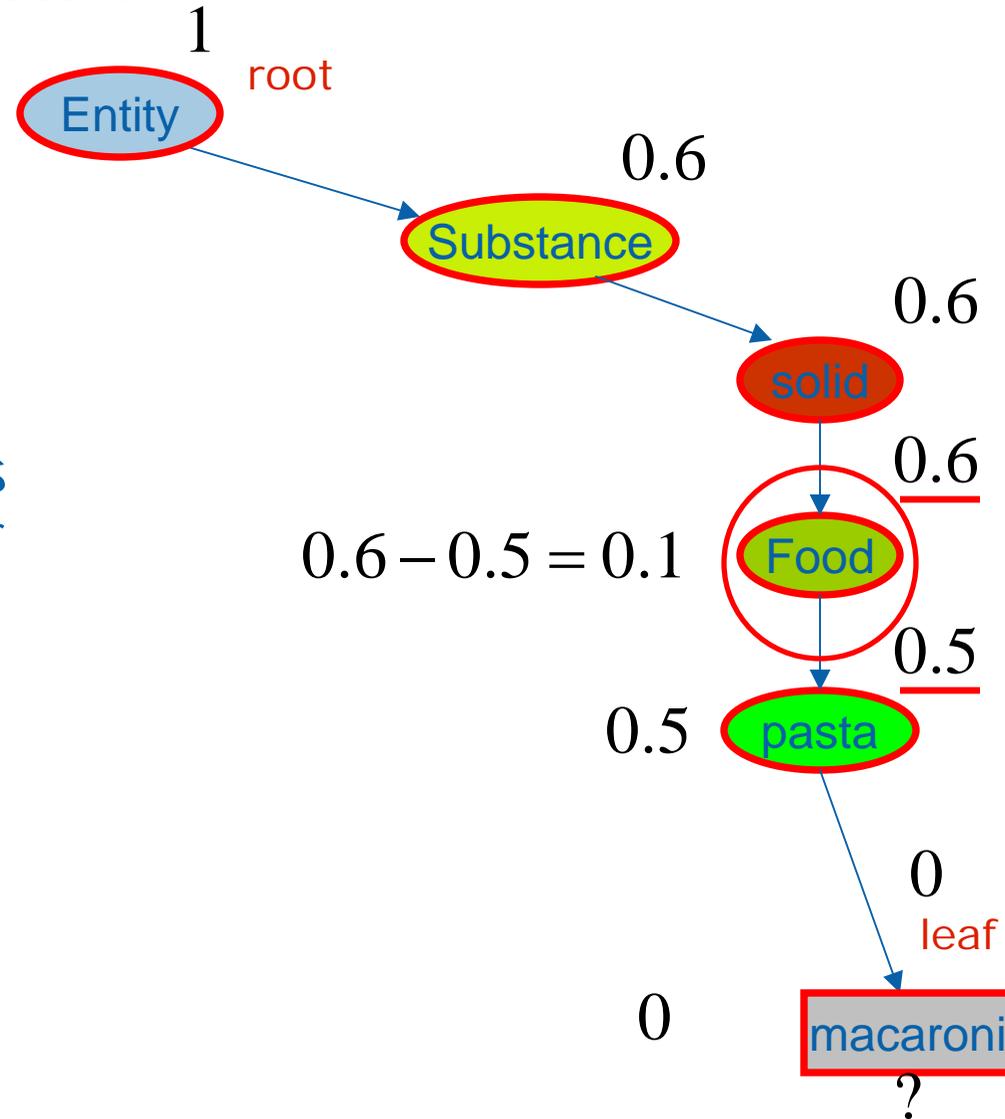
# Shrinkage: Step three

Reduce dependencies  
by subtract counts of  
consecutive nodes

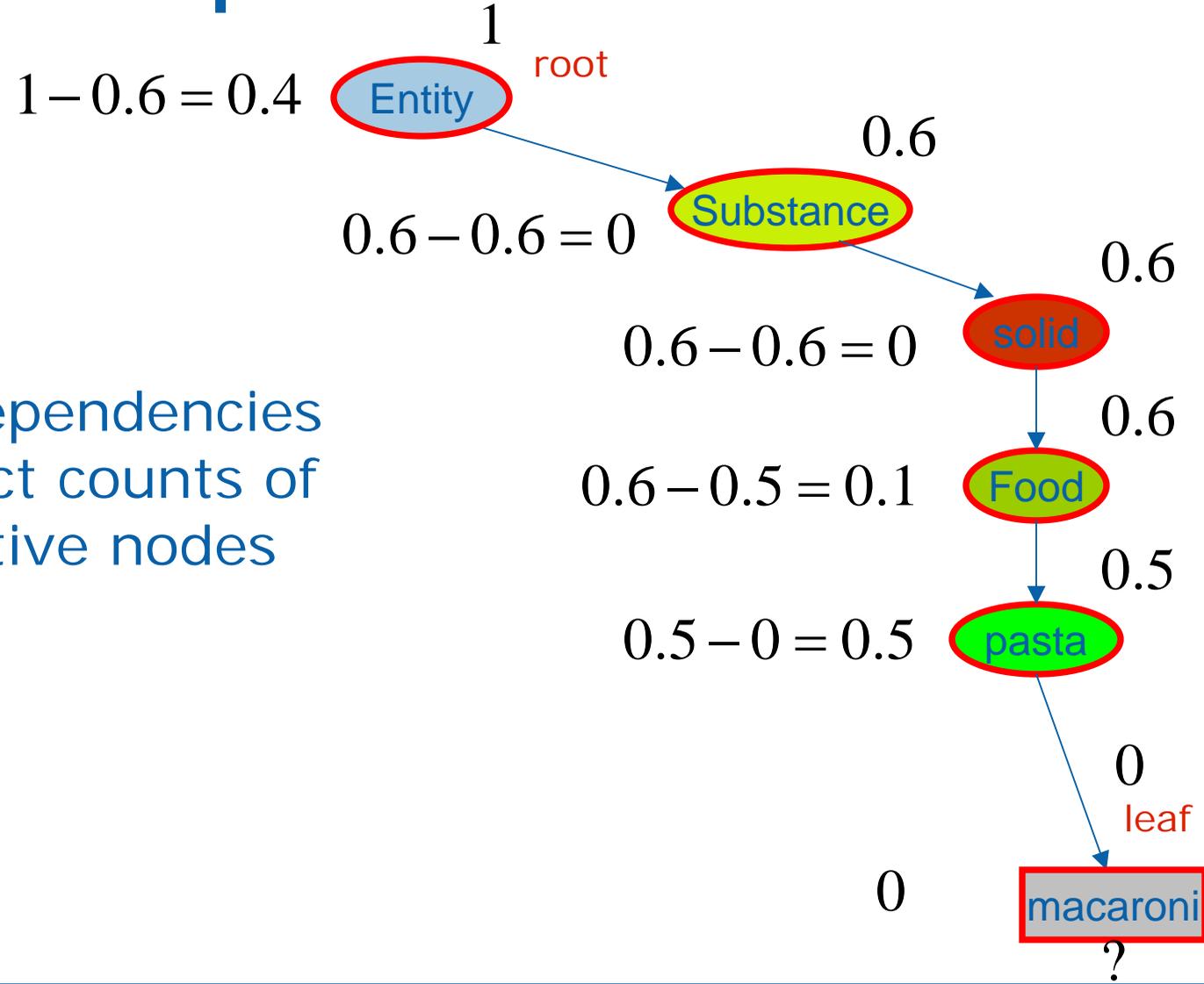


# Shrinkage: Step three

Reduce dependencies  
by subtract counts of  
consecutive nodes



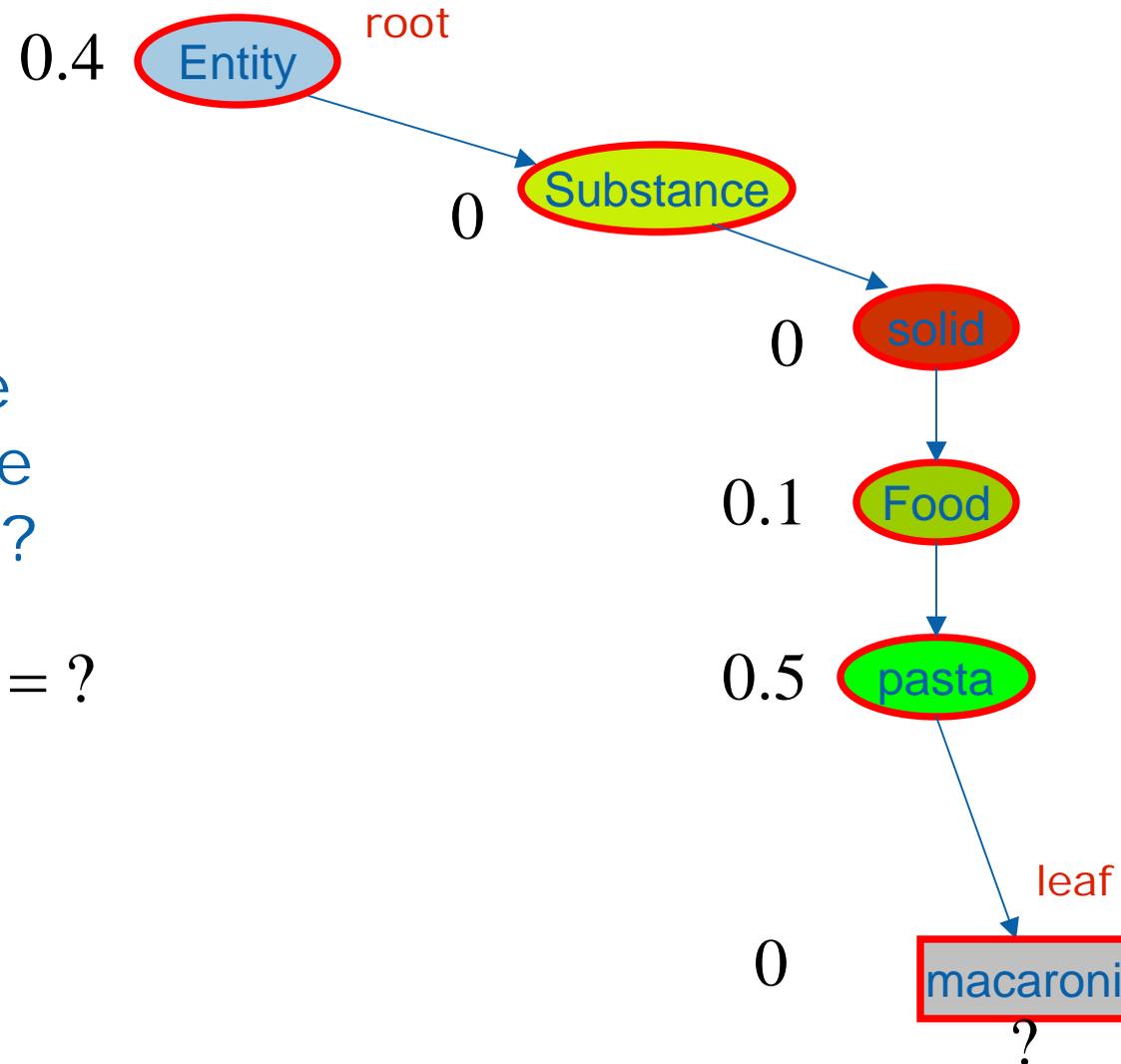
# Shrinkage: Step three



Reduce dependencies  
by subtract counts of  
consecutive nodes



# Shrinkage: Information tradeoff



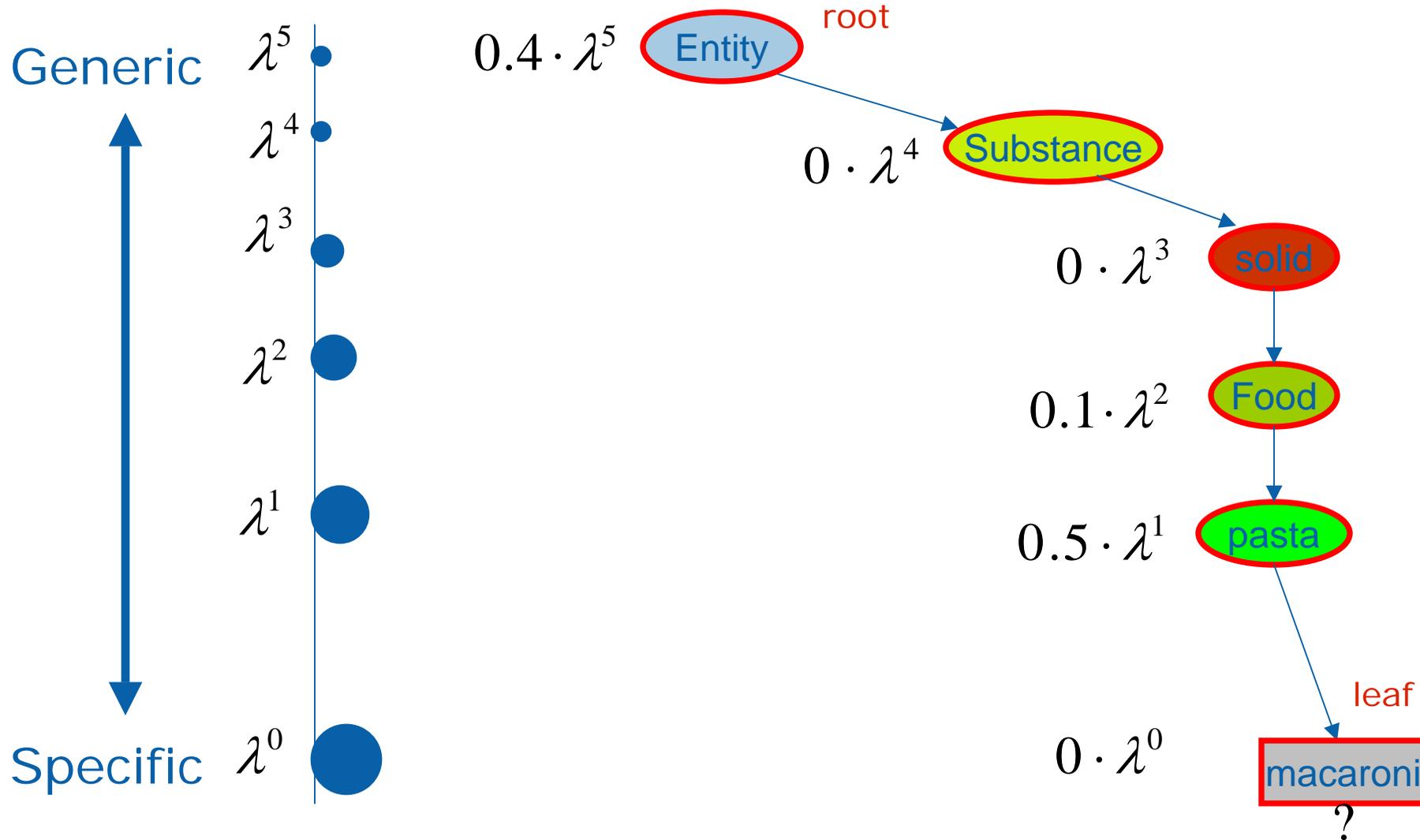
How do we  
combine the  
information?

$$\tilde{p}(\textit{macaroni}) = ?$$

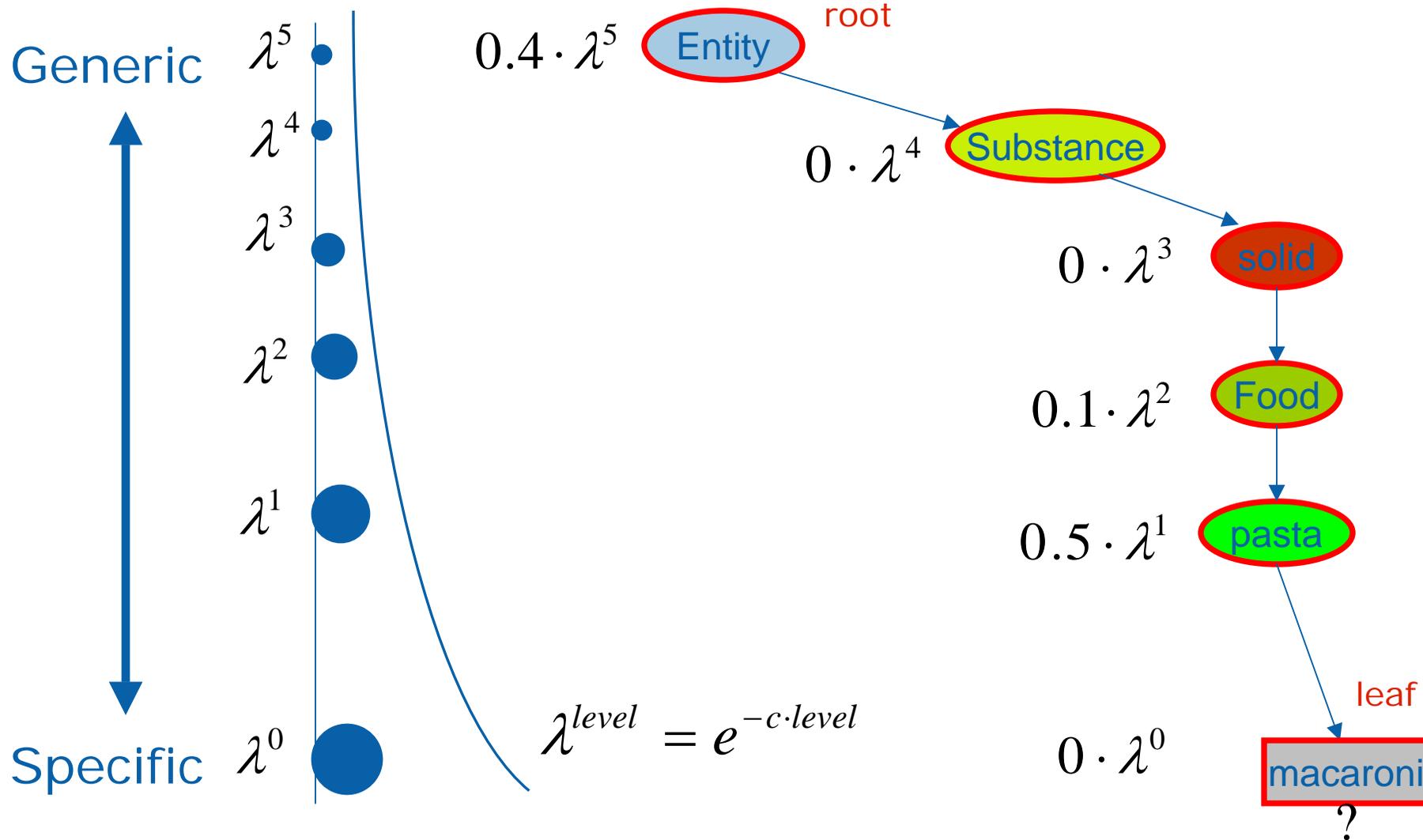
# Shrinkage: Information tradeoff



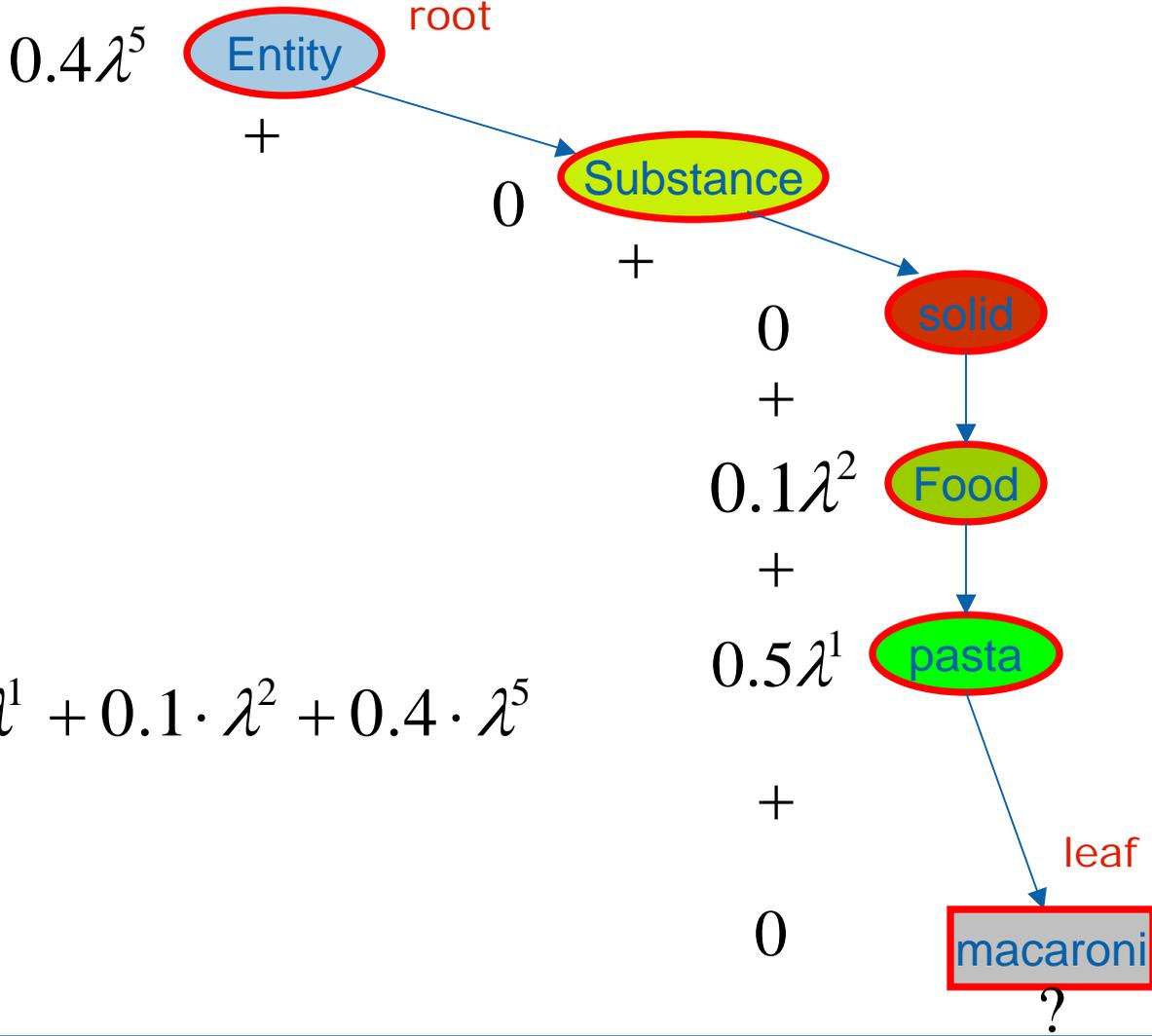
# Shrinkage: Information tradeoff



# Shrinkage: Information tradeoff



# Shrinkage: Information tradeoff



$$\tilde{p}(\text{macaroni}) = 0.5 \cdot \lambda^1 + 0.1 \cdot \lambda^2 + 0.4 \cdot \lambda^5$$



# Advantages of shrinkage

## **1. Create improved probability estimates for the leaf nodes (objects) of the ontology**

The effect of this improvement is a reduction in the number of training examples required to achieve a desired accuracy

## **2. Compute probabilities for objects not present in the models**

The effect is robustness when objects not present in the activity models are used while performing an activity



# Performance on data collected from multiple individuals

- installed 108 RFIDs in real home
- 9 subjects
- 126 examples of 26 activities
- Using RFID glove reader
- **Web mined activity models web**

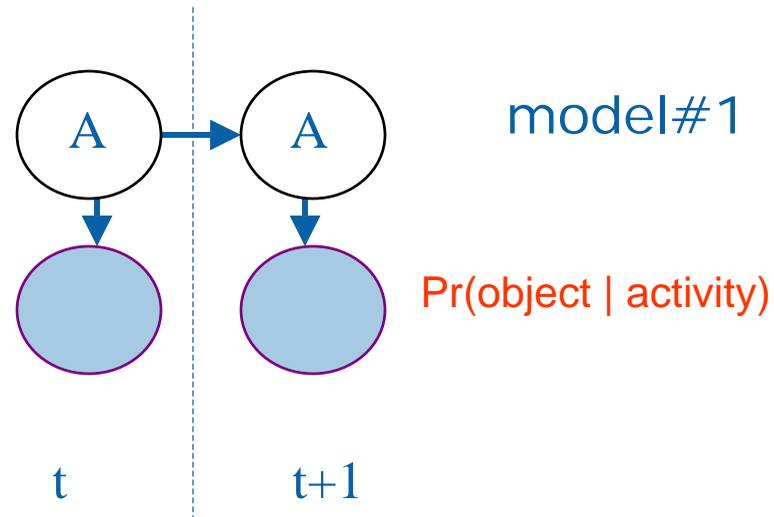


Ontology: generated from 108 tagged objects and objects present in web mined activity models.

**Given trace, infer activities**



# Activities modeled by an HMM



- Single state per activity (26)
- Uniform prior
- Self-transition for smoothing
- Uniform inter-state transition

$$\Pr(a_i) = \frac{1}{26} = 0.04$$

$$\Pr(a_i | a_i) = T_{ii} = 0.8$$

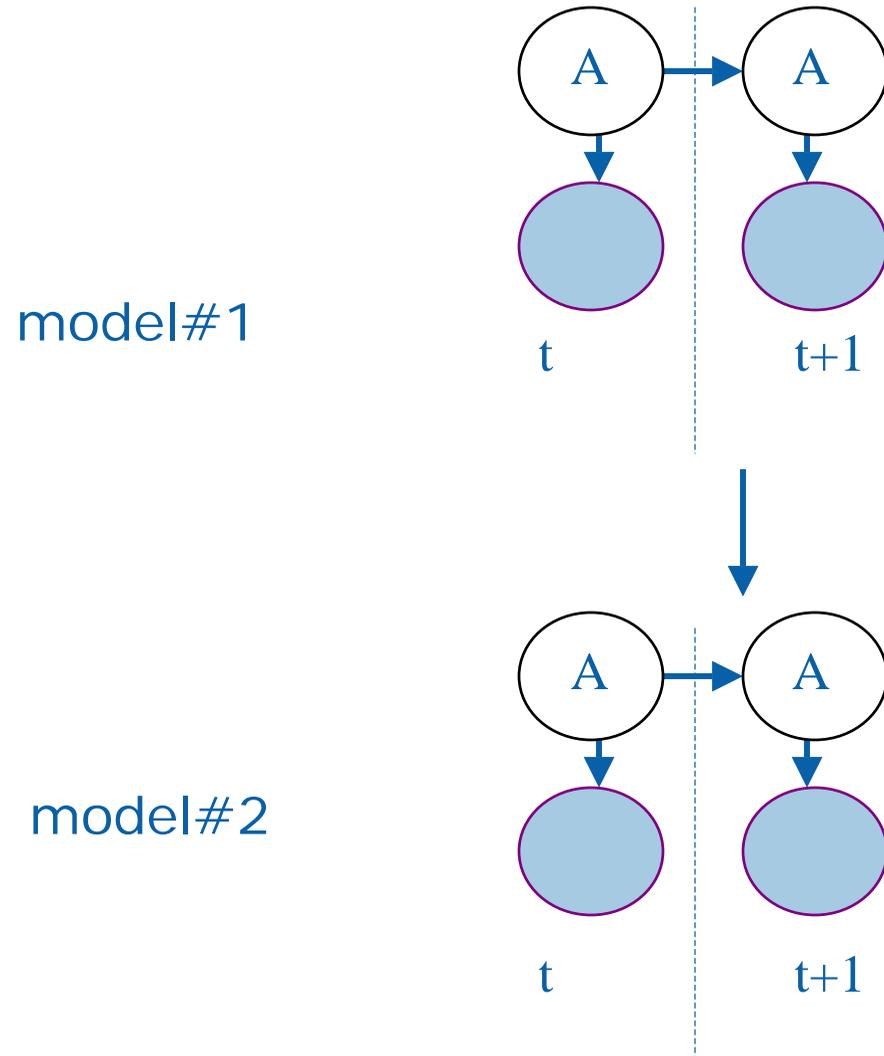
$$\Pr(a_i | a_j) = T_{ij} = \frac{1 - 0.8}{n - 1} = \frac{0.2}{25} = 0.01$$

$P(o | a) =$  mined from web

$T$

	A1	A2	...	A26
A1	0.8	0.01	...	0.01
A2	0.01	0.8	...	0.01
⋮				
A26	0.01	0.01	...	0.8

# Activities modeled by an HMM

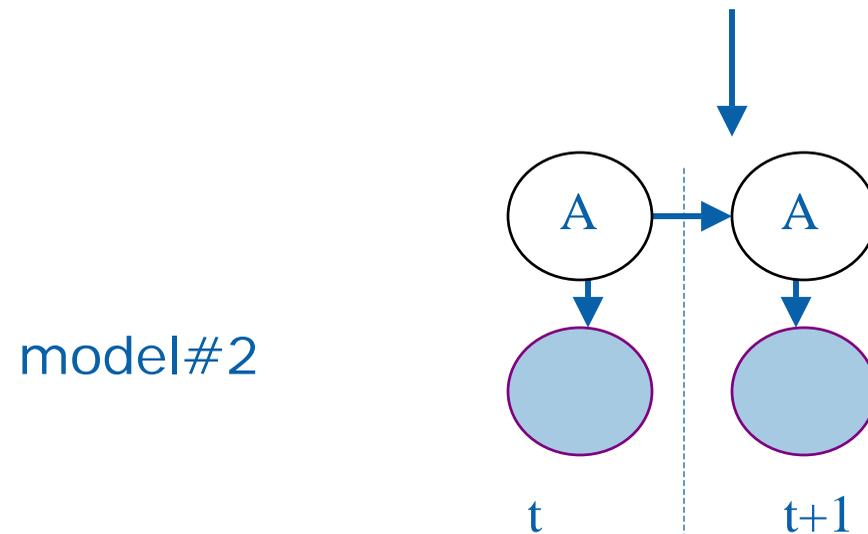
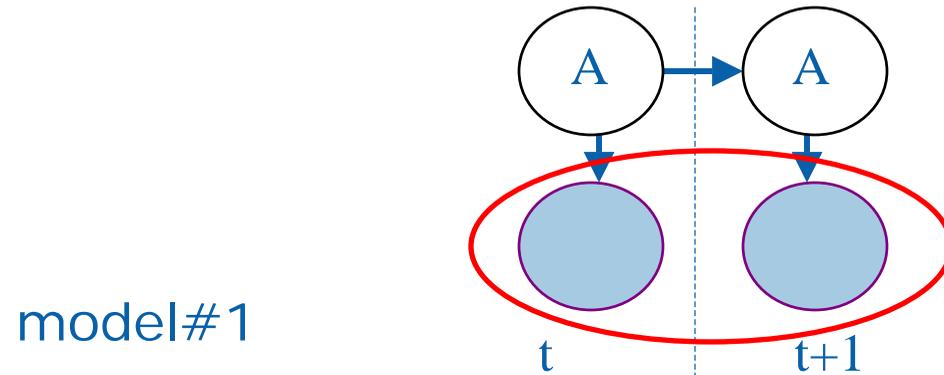


Shrinkage over  
observation matrix  
using

$$H1 = \lambda^{level} = e^{-c \cdot level}$$

$$H2 = \lambda^{level} = 1 / c^{level}$$

# Activities modeled by an HMM



Shrinkage over  
observation matrix  
using

$$H1 = \lambda^{level} = e^{-c \cdot level}$$

$$H2 = \lambda^{level} = 1 / c^{level}$$

# Experiment 1: Improvement of overall accuracy

Assemble all the activity examples in a single sequence

Infer the most likely state (activity) sequence using Viterbi decoding

Compute total accuracy



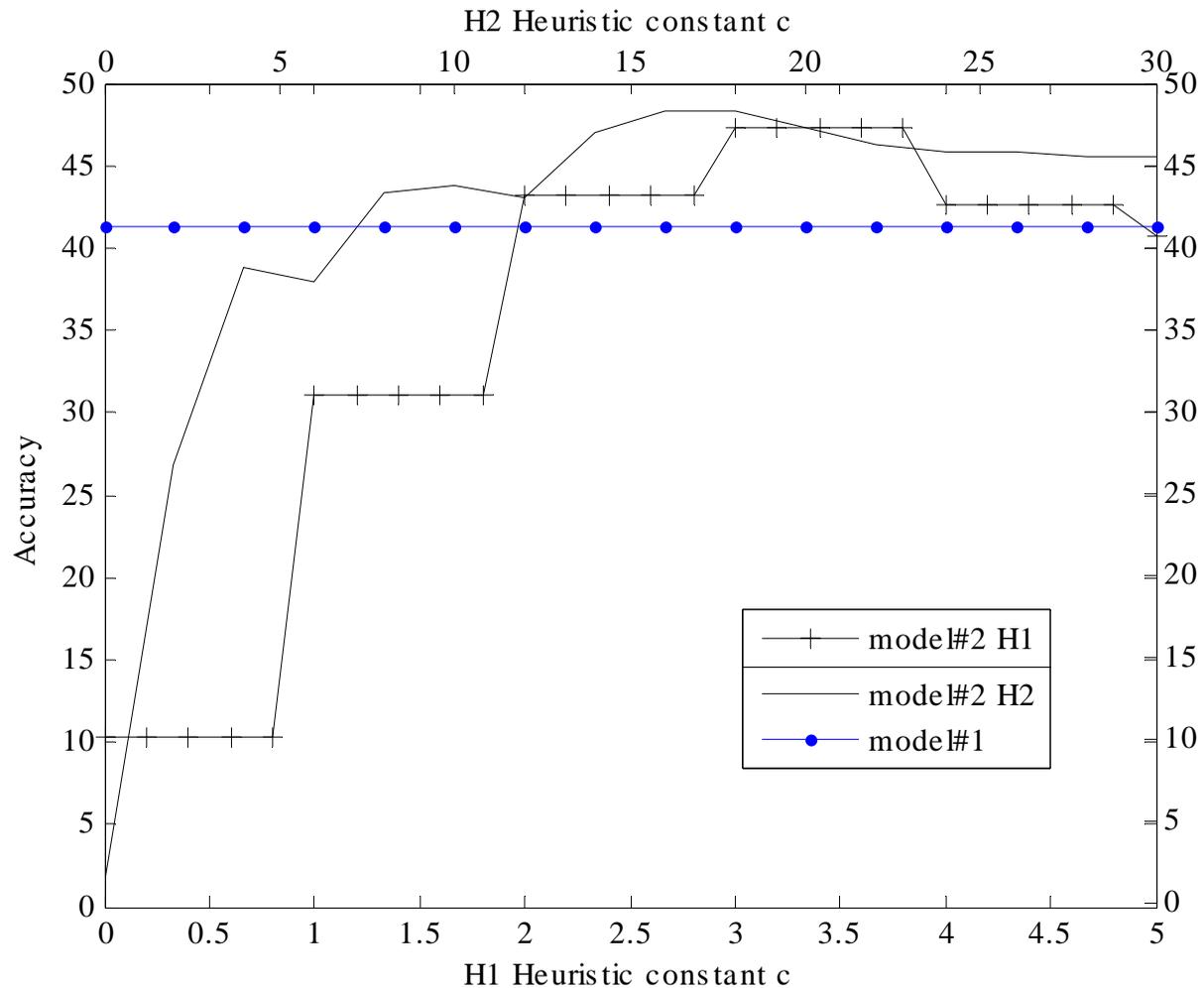
# Shrinkage: Learning the weights

No shrinkage:  
42%

With  
shrinkage:  
48.35%

Improvement:  
15.11%

Bootstrapping  
by learning  
using 126  
sensor traces:  
19.2%



# Experiment 2: Robustness to unseen observations

Replace  $m\%$  of the observations in the activity examples by observations of one of their randomly selected sibling nodes in the ontology

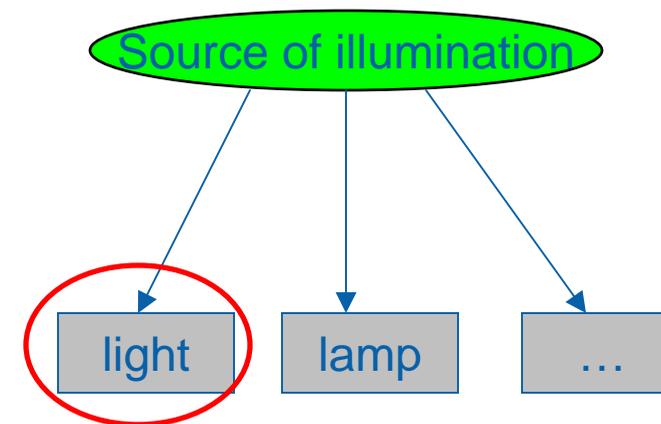
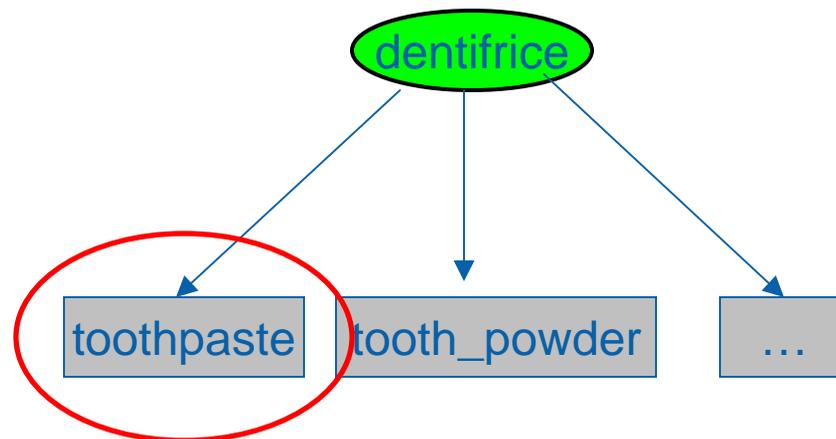
Brushing teeth

Original: light  
Replaced: light

toothpaste  
tooth\_powder

floss  
floss

light  
lamp



# Results: Robustness to unseen observations

When replacing  
100%

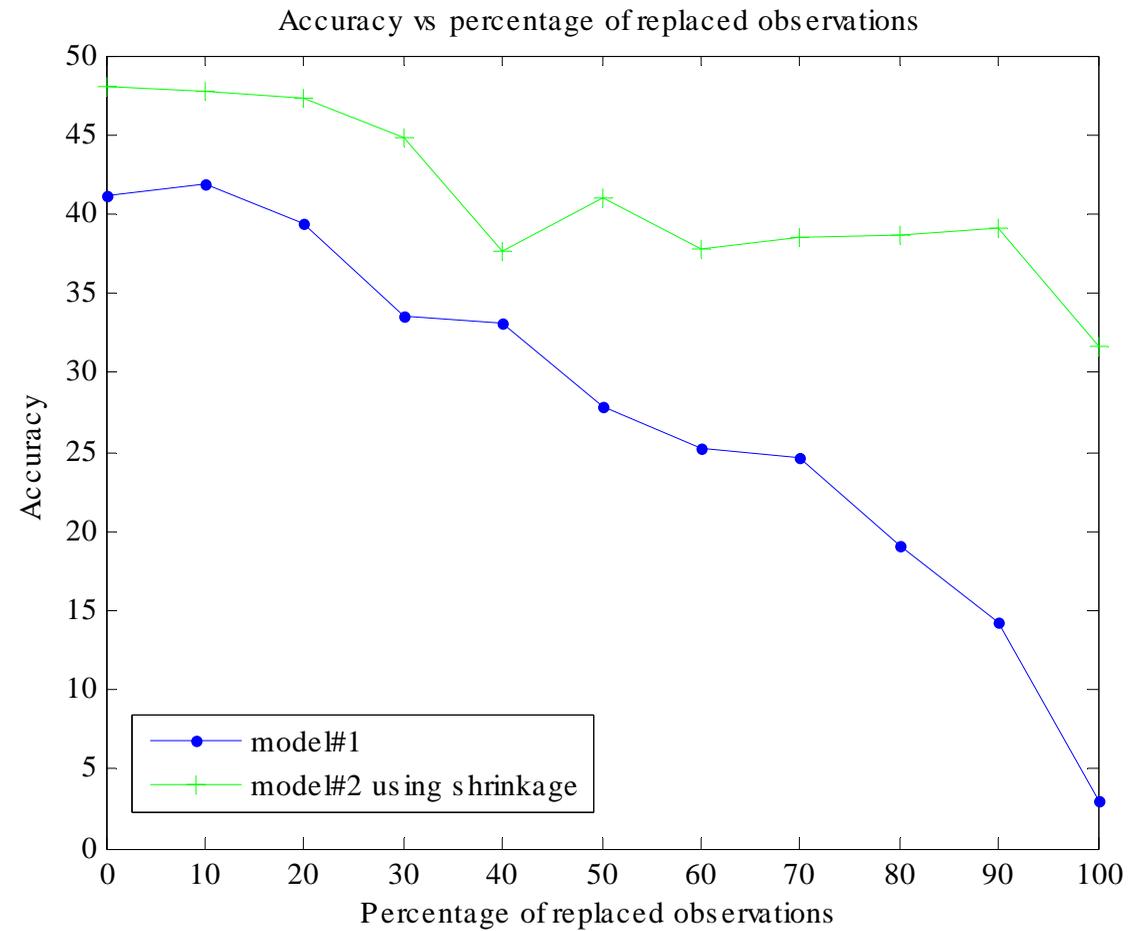
No shrinkage:  
Randomly  
guessing

3.8%

Drops 91.6%

Shrinkage:

Drops 33%



# Effect of limited training data by simulation

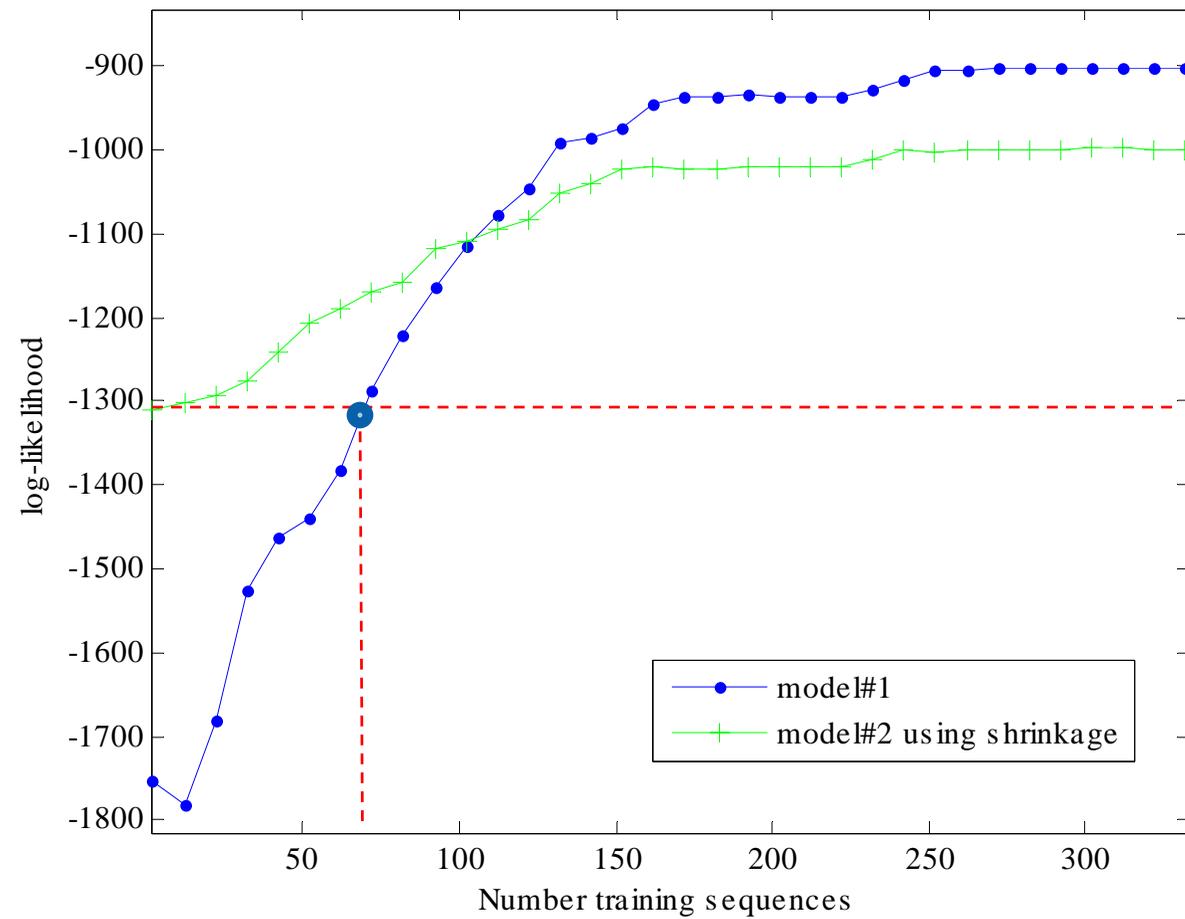
Simulations were performed to investigate the impact of shrinkage with limited training data

The ontology

- was generated from a list of 815 objects
- consists of 4188 nodes
- 815 leaf nodes
- has a maximum depth of 14.



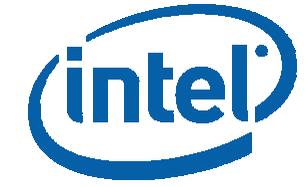
# Experiment: Effect of limited training data



# Conclusion

- Previous work demonstrated that it is possible to mine useful models of *arbitrary* day-to-day activities from the web
- Here we show that it is possible to deal with model incompleteness by incorporating common sense knowledge
- we compute probabilities for objects not originally present in the models
- We can improve the probability estimates
- we can learn higher quality models with less amount of training data
- Towards a completely unsupervised approach to learning activity models





**Thank you!**