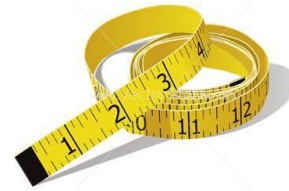
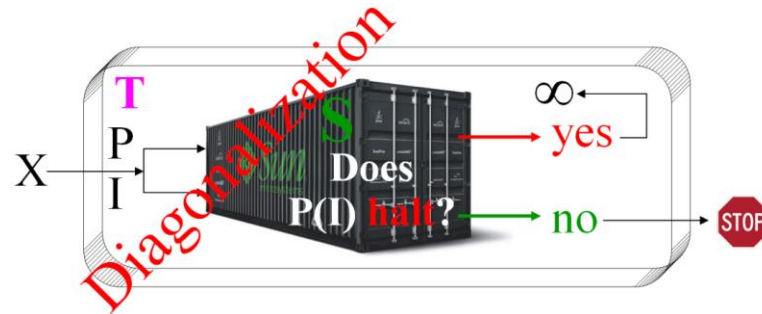


Algorithms

1. Existence

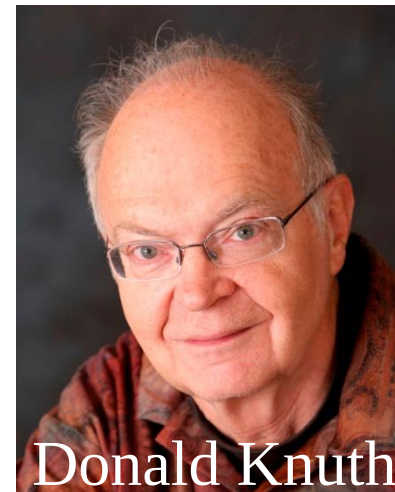
2. Efficiency

- Time
- Space



Worst case behavior analysis as a function of input size

Asymptotic growth: O Ω Θ o ω



Upper Bounds



Definition: $f(n) = O(g(n))$

$$\Leftrightarrow \exists c, k > 0 \ni 0 \leq f(n) \leq c \cdot g(n) \quad \forall n > k$$

$$\Leftrightarrow \lim_{n \rightarrow \infty} f(n) / g(n) \text{ exists}$$

$$O(g(n)) = \{f \mid \exists c, k > 0 \ni 0 \leq f(n) \leq c \cdot g(n) \quad \forall n > k\}$$

“ $f(n)$ is big-O of $g(n)$ ”

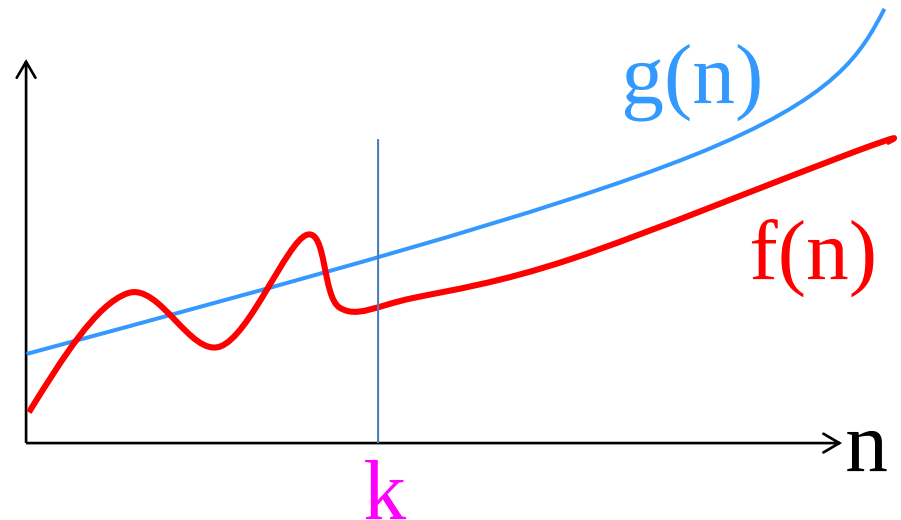
Ex: $n = O(n^2)$

$$33n + 17 = O(n)$$

$$n^8 + n^7 = O(n^{12})$$

$$n^{100} = O(2^n)$$

$$213 = O(1)$$



Lower Bounds



Definition: $f(n) = \Omega(g(n))$

$$\Leftrightarrow g(n) = O(f(n))$$

$$\Leftrightarrow \lim_{n \rightarrow \infty} g(n) / f(n) \text{ exists}$$

$$\Omega(g(n)) = \{f \mid \exists c, k > 0 \ni 0 \leq g(n) \leq c \cdot f(n) \forall n > k\}$$

“ $f(n)$ is Omega of $g(n)$ ”

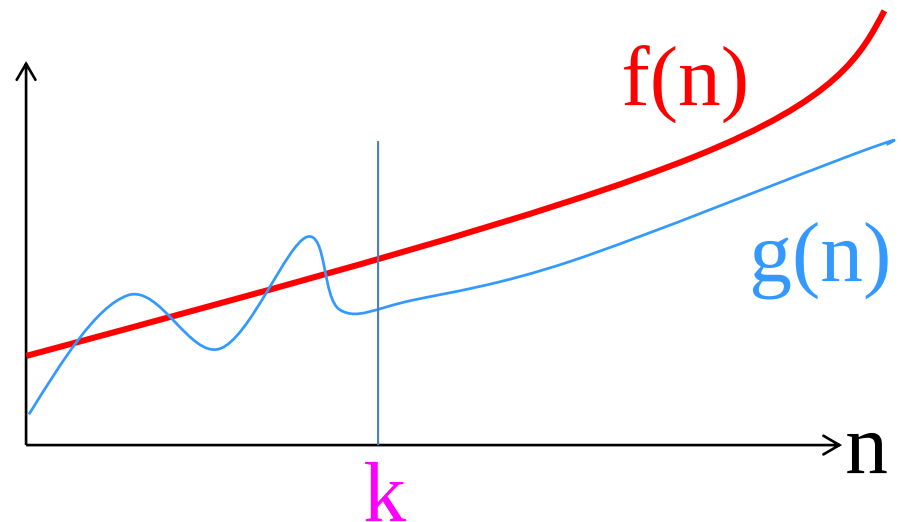
Ex: $100n = \Omega(n)$

$$33n + 17 = \Omega(\log n)$$

$$n^8 - n^7 = \Omega(n^8)$$

$$213 = \Omega(1/n)$$

$$10^{100} = \Omega(1)$$



Tight Bounds



Definition: $f(n) = \Theta(g(n))$

$$\Leftrightarrow f(n) = O(g(n)) \text{ and } g(n) = O(f(n))$$

$$\Leftrightarrow f(n) = O(g(n)) \text{ and } f(n) = \Omega(g(n))$$

$$\Leftrightarrow \lim_{n \rightarrow \infty} g(n)/f(n) \text{ and } \lim_{n \rightarrow \infty} f(n)/g(n) \text{ exist}$$

“ $f(n)$ is Theta of $g(n)$ ”

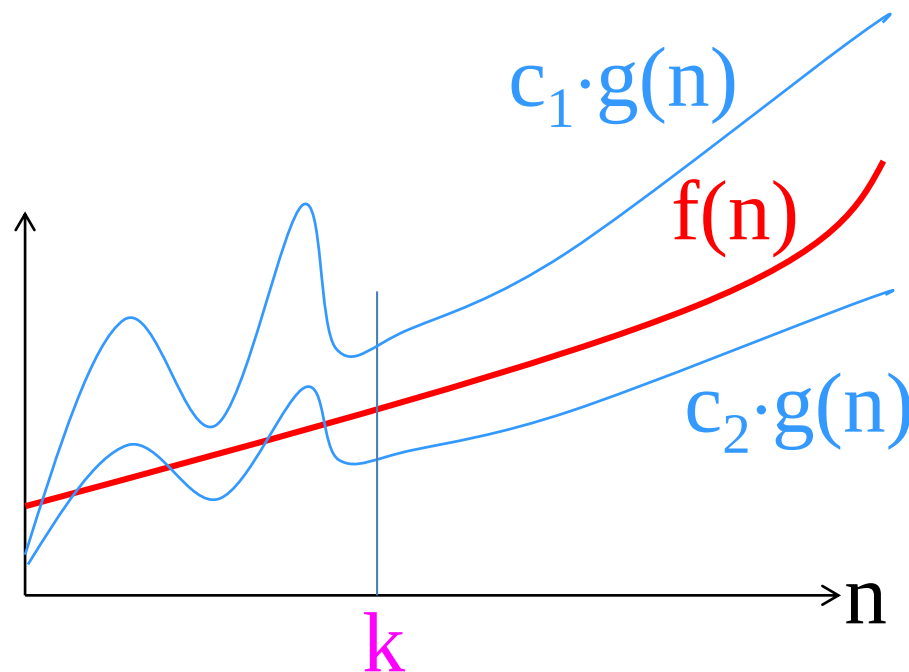
Ex: $99n = \Theta(n)$

$$n + \log n = \Theta(n)$$

$$n^8 - n^7 = \Theta(n^8)$$

$$n^2 + \cos(n) = \Theta(n^2)$$

$$213 = \Theta(1)$$



Loose Bounds



Definition: $f(n) = o(g_1(n))$

$$\Leftrightarrow f(n) = O(g_1(n)) \text{ and } f(n) \neq \Omega(g_1(n))$$

“ $f(n)$ is little-o of $g_1(n)$ ”

Definition: $f(n) = \omega(g_2(n))$

$$\Leftrightarrow f(n) = \Omega(g_2(n)) \text{ and } f(n) \neq O(g_2(n))$$

“ $f(n)$ is little-omega of $g_2(n)$ ”

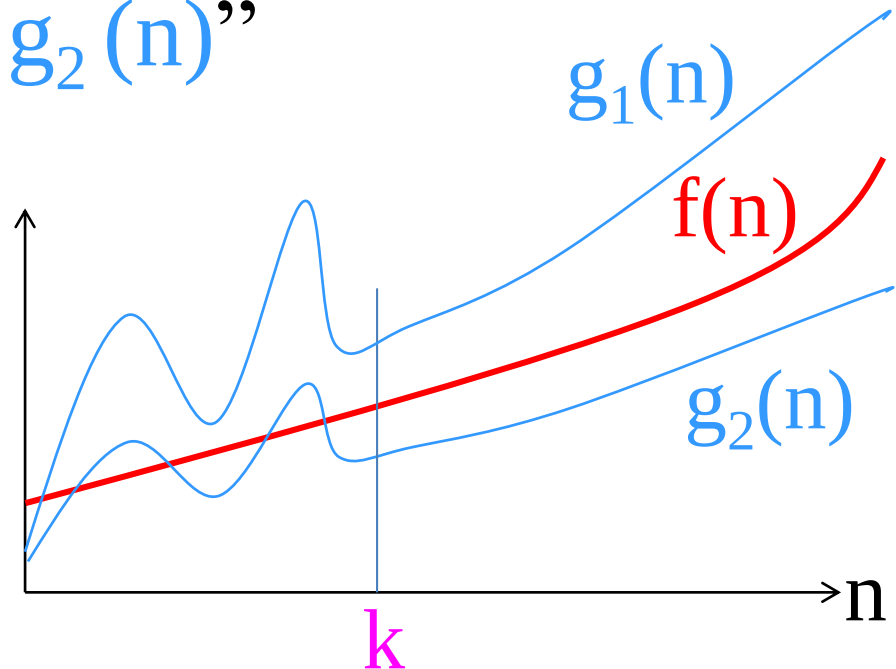
Ex: $8n = o(n \log \log n)$

$$n \log n = \omega(n)$$

$$n^6 = o(n^{6.01})$$

$$n^2 + \sin(n) = \omega(n)$$

$$213 = o(\log n)$$



Growth Laws



Let $f_1(n) = O(g_1(n))$ and $f_2(n) = O(g_2(n))$

Thm: $f_1(n) + f_2(n) = O(\max(g_1(n), g_2(n)))$

- Sequential code

Thm: $f_1(n) \cdot f_2(n) = O(g_1(n) \cdot g_2(n))$

- Nested loops & subroutine calls

Thm: $n^k = O(c^n) \quad \forall c, k > 0$

Ex: $n^{1000} = O(1.001^n)$

Solving Recurrences



$$T(n) = a \cdot T(n/b) + f(n)$$

$$a \geq 1, b > 1, \text{ and let } c = \log_b a$$

$$\text{Thm: } f(n) = O(n^{c-\varepsilon}) \text{ for some } \varepsilon > 0 \Rightarrow T(n) = \Theta(n^c)$$

$$f(n) = \Theta(n^c) \Rightarrow T(n) = \Theta(n^c \log n)$$

$$f(n) = \Omega(n^{c+\varepsilon}) \text{ some } \varepsilon > 0 \text{ and } a \cdot f(n/b) \leq d \cdot f(n) \\ \text{for some } d < 1 \ \forall \ n > n_0 \Rightarrow T(n) = \Theta(f(n))$$

$$\text{Ex: } T(n) = 2T(n/2) + n \Rightarrow T(n) = \Theta(n \log n)$$

$$T(n) = 9T(n/3) + n \Rightarrow T(n) = \Theta(n^2)$$

$$T(n) = T(2n/3) + 1 \Rightarrow T(n) = \Theta(\log n)$$

Stirling's Formula

Factorial: $n! = 1 \cdot 2 \cdot 3 \cdot \dots \cdot (n-2) \cdot (n-1) \cdot n$

Theorem: $n! = \sqrt{2\pi n} \cdot \left(\frac{n}{e}\right)^n \cdot \left(1 + \Theta\left(\frac{1}{n}\right)\right)$

where e is Euler's constant $= 2.71828\dots$

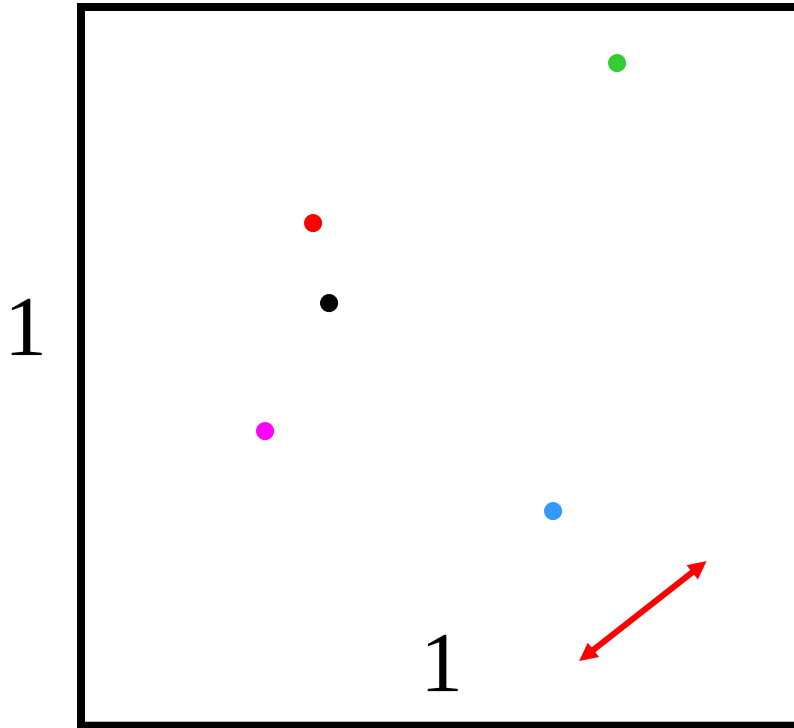
Theorem: $n! \approx \sqrt{2\pi n} \cdot \left(\frac{n}{e}\right)^n$

Corollary: $\log(n!) \approx \log\left(\sqrt{2\pi n} \cdot \left(\frac{n}{e}\right)^n\right) = n \cdot \log\left(\frac{n}{e}\right) + \frac{\log(2\pi n)}{2} = O(n \log n)$

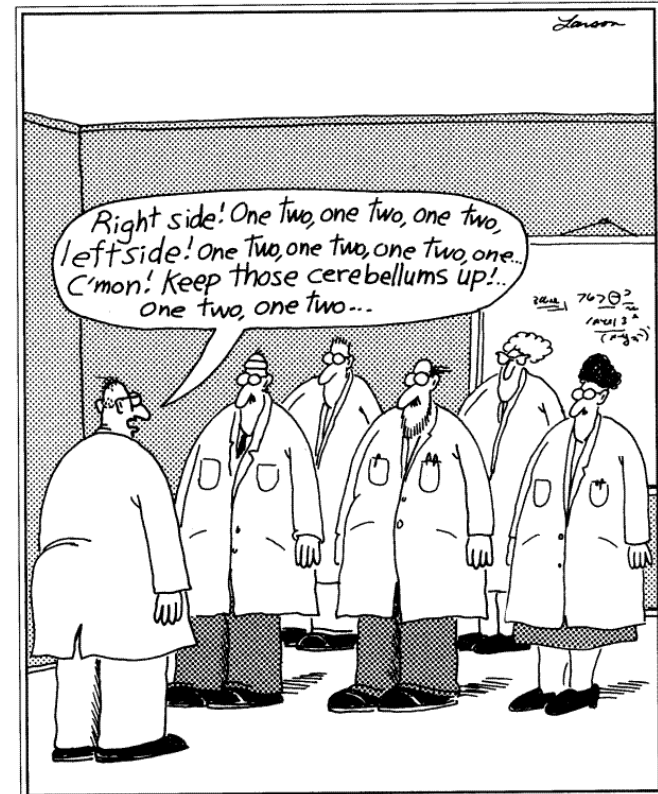
$$\log(n!) = O(n \log n)$$

- Useful in analyses and bounds

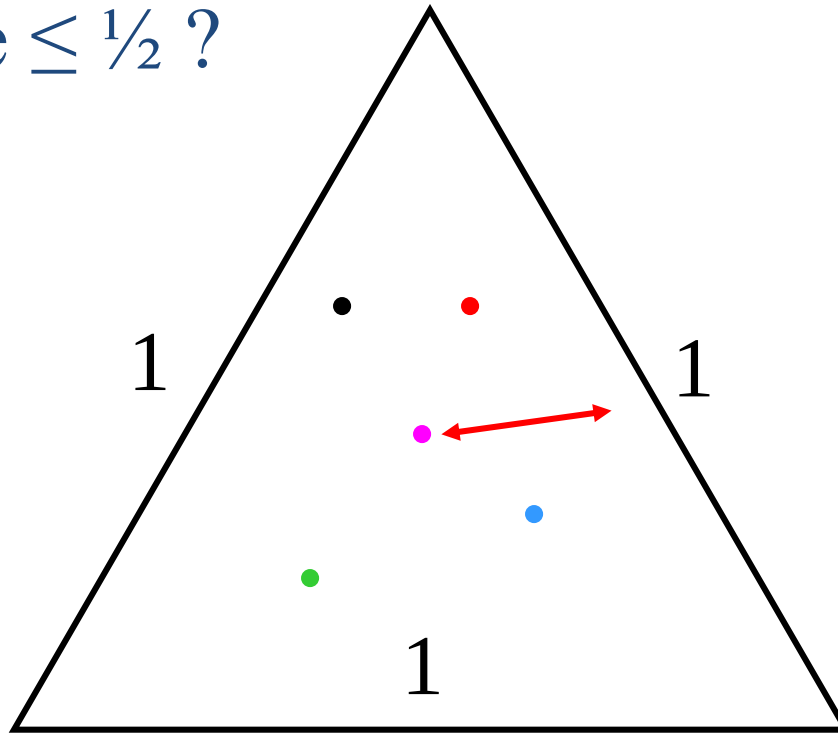
Problem: Given any five points in/on the unit square, is there always a pair with distance $\leq \frac{1}{\sqrt{2}}$?



- What approaches fail?
- What techniques work and why?
- Lessons and generalizations



Problem: Given any five points in/on the unit equilateral triangle, is there always a pair with distance $\leq \frac{1}{2}$?

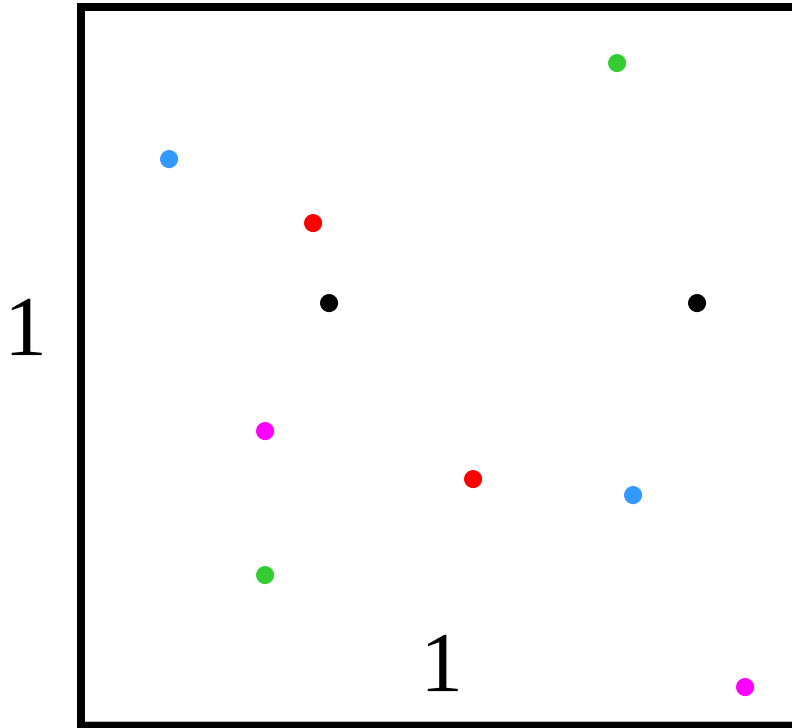


- What approaches fail?
- What techniques work and why?
- Lessons and generalizations

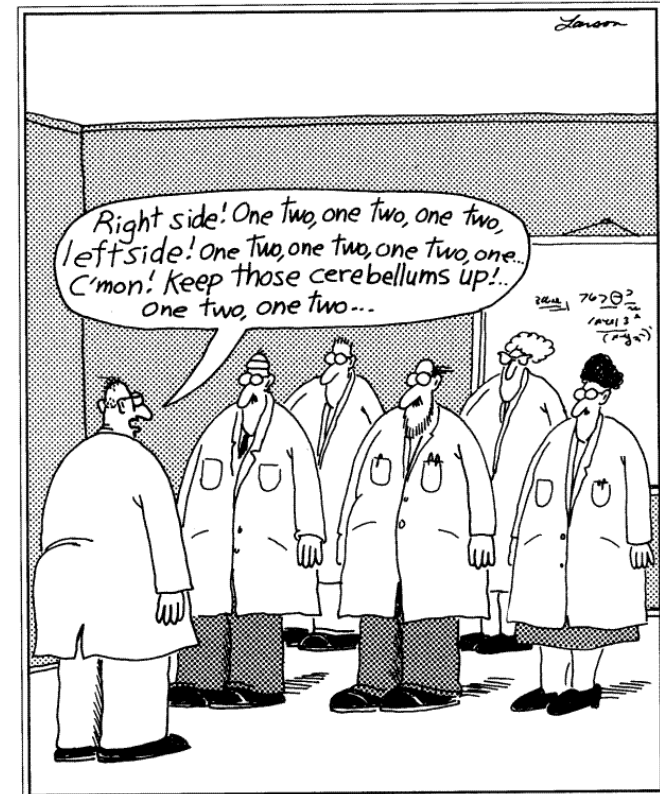


Math phobic's nightmare

Problem: Given any ten points in/on the unit square, what is the maximum pairwise distance?



- What approaches fail?
- What techniques work and why?
- Lessons and generalizations

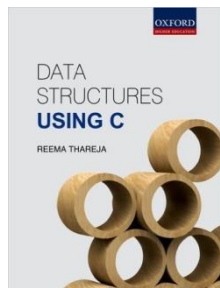
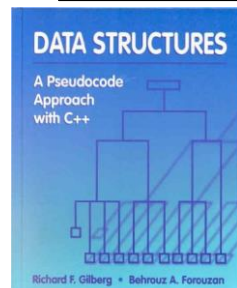
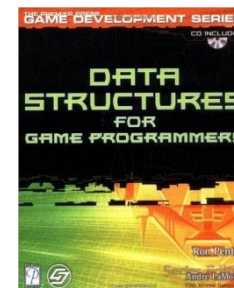
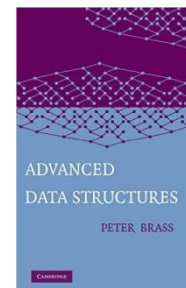
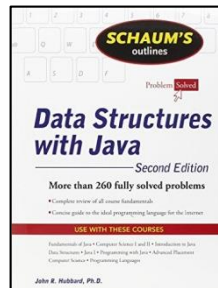
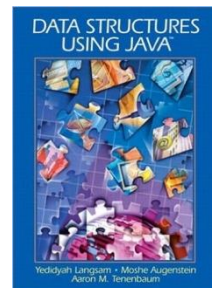
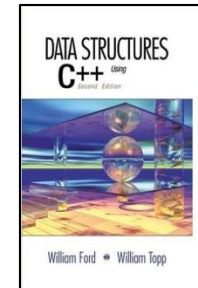
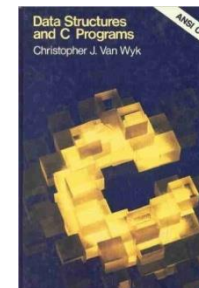
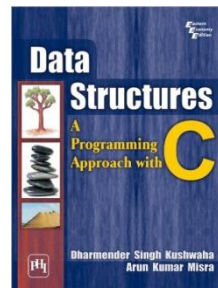
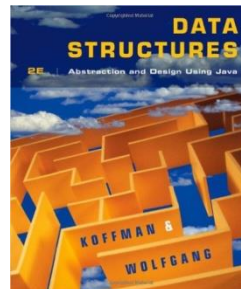
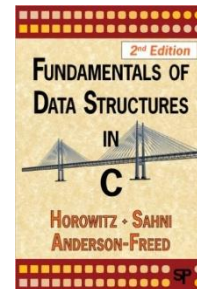
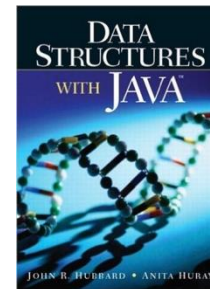
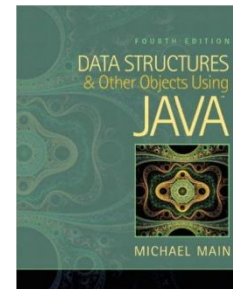
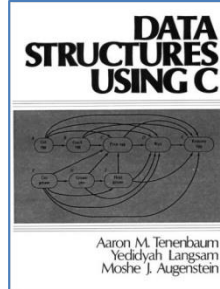
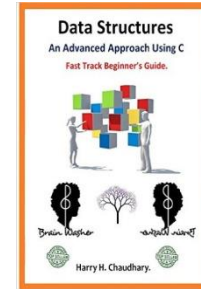
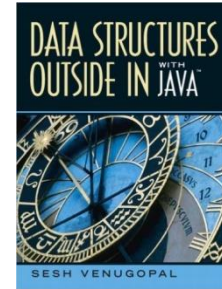


Data Structures



Data Structures

- Techniques for organizing information effectively
- Allowed operations:
 - Initialize
 - Insert
 - Delete
 - Search
 - Min/max
 - Successor
 - Predecessor
 - Merge
 - Split
 - Revert



Data Structures

Primitive types:

1. Boolean
2. Character
3. Floating-point
4. Double
5. Integer
6. Enumerated type

Abstract data types:

7. **Array**
8. Container
9. Map
10. Associative array
11. Dictionary
12. Multimap
13. **List**
14. Set
15. Multiset / Bag
16. **Priority queue**
17. **Queue**
18. Double-ended queue
19. **Stack**
20. String
21. **Tree**
22. **Graph**

Composite types:

23. **Array**
24. Record
25. Union
26. Tagged union

Arrays:

27. **Bit array**
28. Bit field
29. Bitboard
30. **Bitmap**
31. Circular buffer
32. Control table
33. Image
34. Dynamic array
35. Gap buffer
36. Hashed array tree
37. Heightmap
38. **Lookup table**
39. **Matrix**
40. Parallel array
41. **Sorted array**
42. **Sparse array**
43. Sparse matrix
44. Iliffe vector
45. Variable-length array

Lists:

46. **Doubly linked list**
47. Array list
48. **Linked list**
49. Self-organizing list
50. Skip list
51. Unrolled linked list
52. VList
53. Xor linked list
54. Zipper
55. Doubly connected edge list
56. Difference list
57. Free list

Binary trees:

58. AA tree
59. **AVL tree**
60. **Binary search tree**
61. **Binary tree**
62. Cartesian tree
63. Order statistic tree
64. Pagoda
65. Randomized binary search tree
66. **Red-black tree**
67. Rope

Data Structures

Binary trees (continued):

- 68. Scapegoat tree
- 69. Self-balancing search tree
- 70. Splay tree
- 71. T-tree
- 72. Tango tree
- 73. Threaded binary tree
- 74. Top tree
- 75. Treap
- 76. Weight-balanced tree
- 77. Binary data structure

Trees:

- 78. Trie
- 79. Radix tree
- 80. Suffix tree
- 81. Suffix array
- 82. Compressed suffix array
- 83. FM-index
- 84. Generalised suffix tree
- 85. B-trie
- 86. Judy array
- 87. X-fast trie
- 88. Y-fast trie
- 89. Ctrie

B-trees:

- 90. B-tree
- 91. B+ tree
- 92. B*-tree
- 93. B sharp tree
- 94. Dancing tree
- 95. 2-3 tree
- 96. 2-3-4 tree
- 97. Queap
- 98. Fusion tree
- 99. Bx-tree
- 100. AList

Heaps:

- 101. Heap
- 102. Binary heap
- 103. Weak heap
- 104. Binomial heap
- 105. Fibonacci heap
- 106. AF-heap
- 107. Leonardo Heap
- 108. 2-3 heap
- 109. Soft heap
- 110. Pairing heap
- 111. Leftist heap
- 112. Treap

- 113. Beap
- 114. Skew heap
- 115. Ternary heap
- 116. D-ary heap
- 117. Brodal queue

Multiway trees:

- 118. Ternary tree
- 119. K-ary tree
- 120. And-or tree
- 121. (a,b)-tree
- 122. Link/cut tree
- 123. SPQR-tree
- 124. Spaghetti stack
- 125. Disjoint-set data structure
- 126. Fusion tree
- 127. Enfilade
- 128. Exponential tree
- 129. Fenwick tree
- 130. Van Emde Boas tree
- 131. Rose tree

Space-partitioning trees:

- 132. Segment tree
- 133. Interval tree
- 134. Range tree

Data Structures

Space-partitioning trees (cont):

- 135. Bin
- 136. Kd-tree
- 137. Implicit kd-tree
- 138. Min/max kd-tree
- 139. Adaptive k-d tree
- 140. Quadtree
- 141. Octree
- 142. Linear octree
- 143. Z-order
- 144. UB-tree
- 145. R-tree
- 146. R+ tree
- 147. R* tree
- 148. Hilbert R-tree
- 149. X-tree
- 150. Metric tree
- 151. Cover tree
- 152. M-tree
- 153. VP-tree
- 154. BK-tree
- 155. Bounding interval hierarchy
- 156. BSP tree
- 157. Rapidly exploring random tree

Application-specific trees:

- 158. Abstract syntax tree
- 159. Parse tree
- 160. Decision tree
- 161. Alternating decision tree
- 162. Minimax tree
- 163. Expectiminimax tree
- 164. Finger tree
- 165. Expression tree
- 166. Log-structured merge-tree

Hashes:

- 167. Bloom filter
- 168. Count-Min sketch
- 169. Distributed hash table
- 170. Double Hashing
- 171. Dynamic perfect hash table
- 172. Hash array mapped trie
- 173. Hash list
- 174. Hash table
- 175. Hash tree
- 176. Hash trie
- 177. Koorde
- 178. Prefix hash tree
- 179. Rolling hash

- 180. MinHash
- 181. Quotient filter
- 182. Ctrie

Graphs:

- 183. Graph
- 184. Adjacency list
- 185. Adjacency matrix
- 186. Graph-structured stack
- 187. Scene graph
- 188. Binary decision diagram
- 189. 0-suppressed decision diagram
- 190. And-inverter graph
- 191. Directed graph
- 192. Directed acyclic graph
- 193. Propositional dir. acyclic graph
- 194. Multigraph
- 195. Hypergraph

Other:

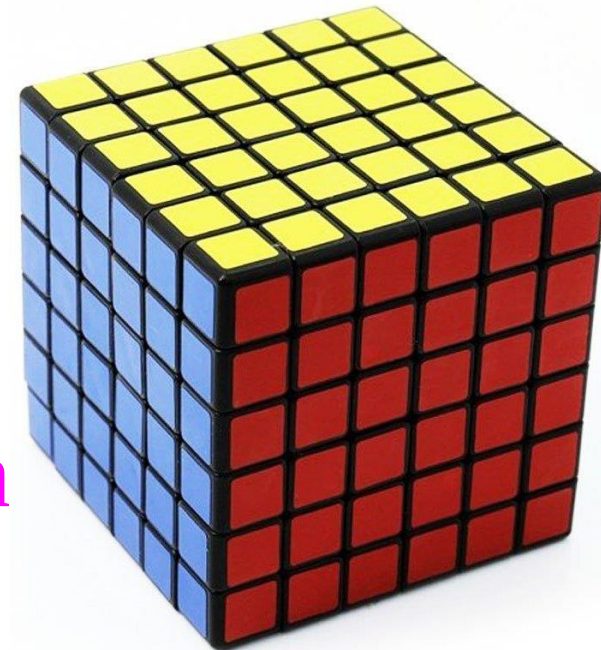
- 196. Lightmap
- 197. Winged edge
- 198. Doubly connected edge list
- 199. Quad-edge
- 200. Routing table
- 201. Symbol table

Arrays

- Sequence of "indexible" locations

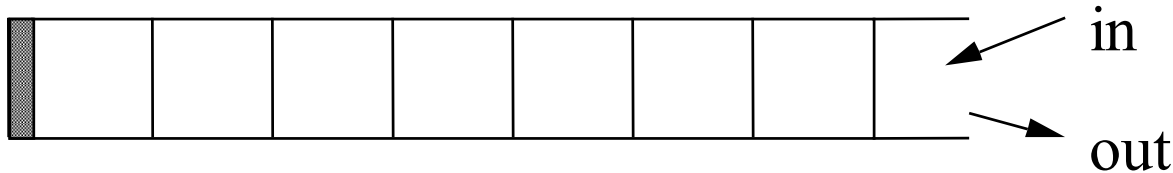
1	2	3	4	5	6	7	...
---	---	---	---	---	---	---	-----

- Unordered:
 - $O(1)$ to add
 - $O(n)$ to search / delete
 - $O(n)$ for min / max
- Ordered:
 - $O(n)$ to add / delete
 - $O(\log n)$ to (binary) search
 - $O(1)$ for min / max

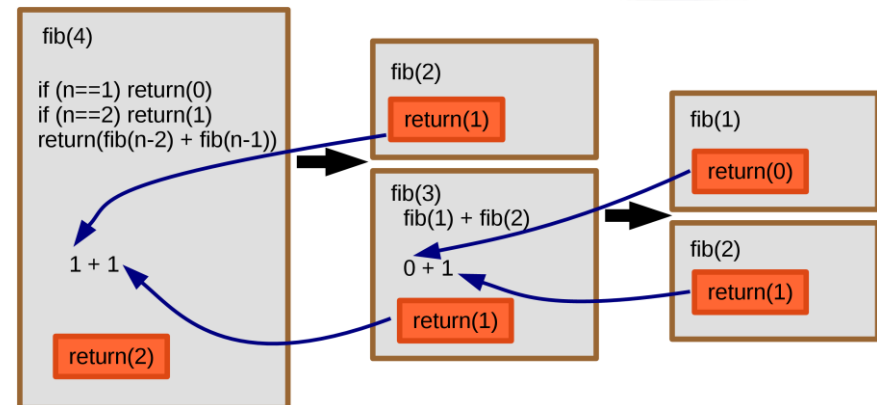


Stacks

- **LIFO** (Last-In First-Out)



- Operations: **push** / **pop** $O(1)$ each
- Can not access “middle”
- Analogy: trays/plates at cafeteria
- Applications:
 - Recursion
 - Compiling / parsing
 - Dynamic binding
 - Web surfing

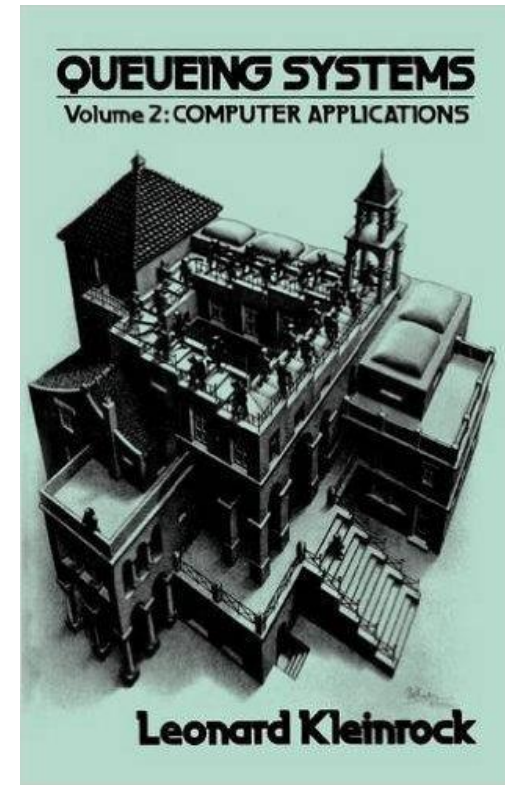


Queues

- **FIFO** (First-In First-Out)



- Operations: **push** / **pop** $O(1)$ each
- Can not access “middle”
- Analogy: line at the store
- Applications:
 - Simulations
 - Scheduling
 - Networks
 - Operating systems

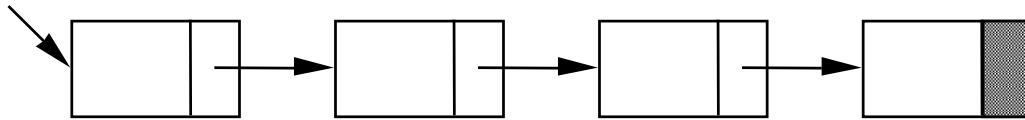


Linked Lists

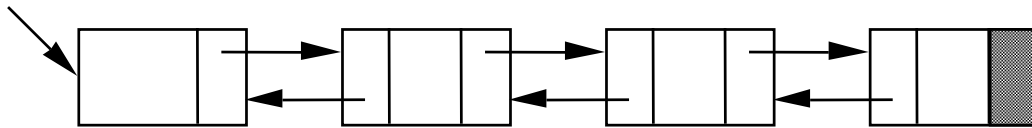
- Successor / predecessor pointers

- Types:

- Single linked



- Double linked

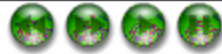
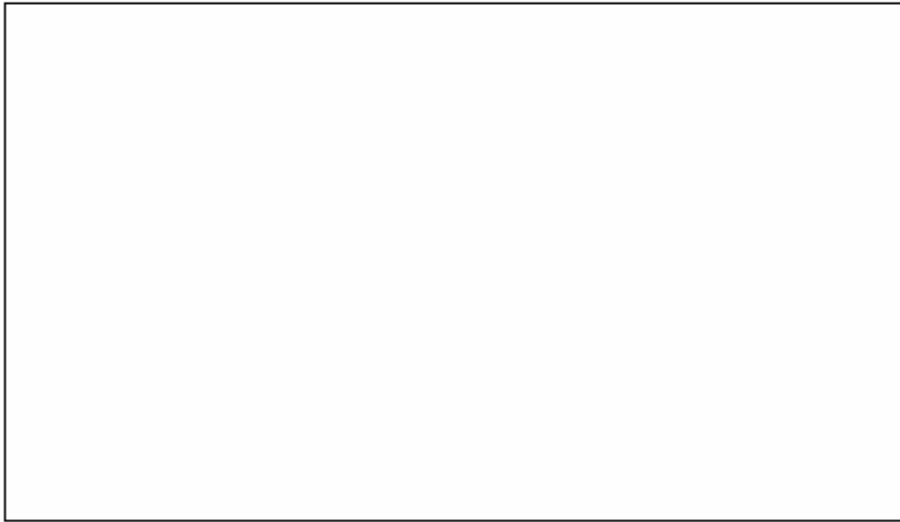


- Circular

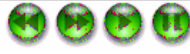
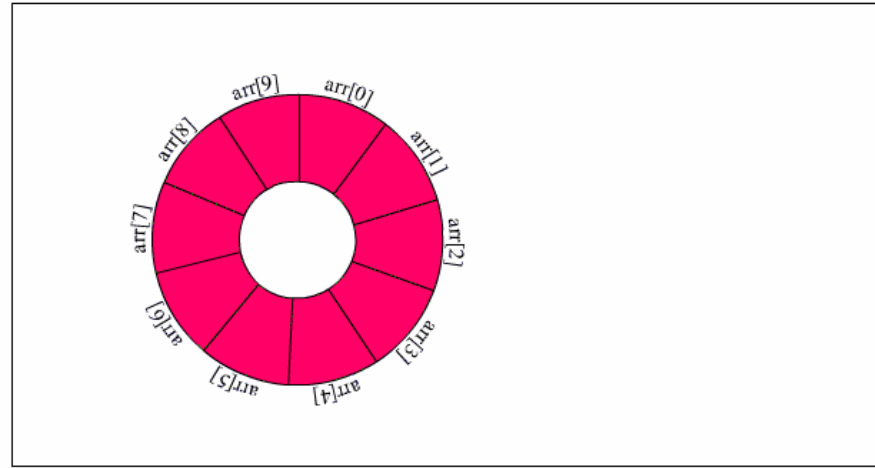
- Operations:

- **Add**: $O(1)$ time
 - **Search**: $O(n)$ time
 - **Delete**: $O(1)$ time (given pointer)

Building a linked list

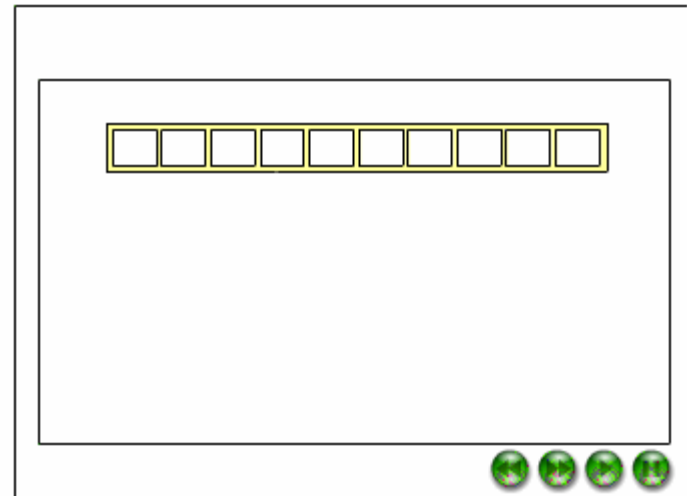
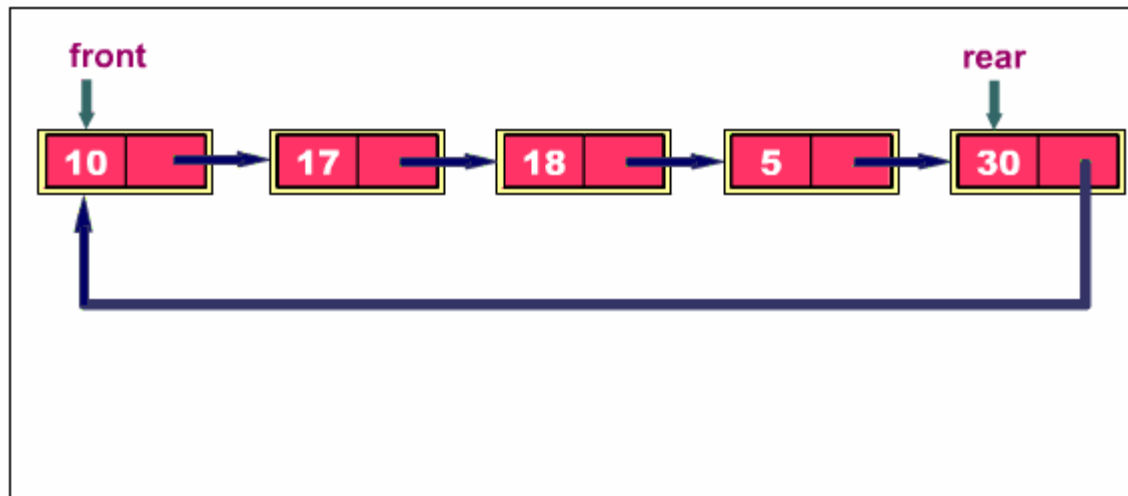


Building of Circular Queue

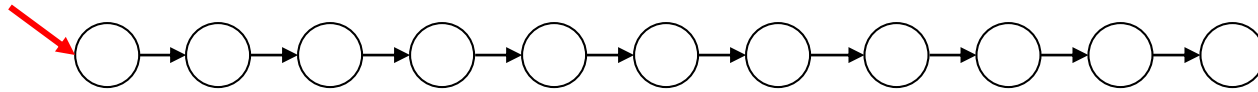


Circular queue as a linked list

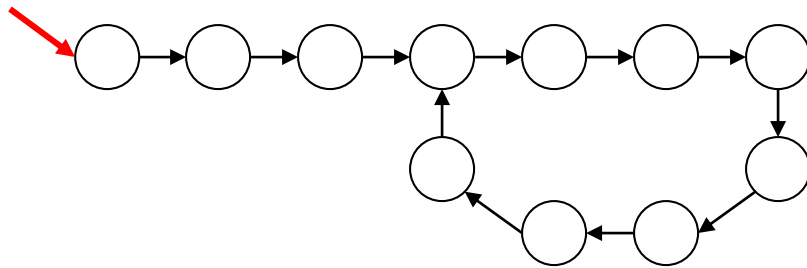
Deletion of a node



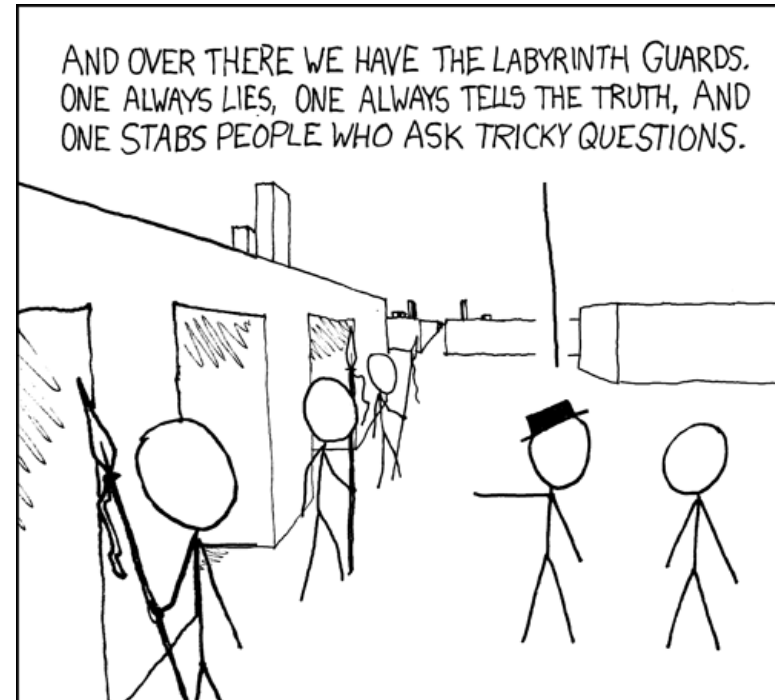
Extra Credit Problem: Given a pointer to a **read-only** (unmodifiable) linked list containing an **unknown number** of nodes n , devise an **$O(n)$** -time and **$O(1)$** space algorithm that determines whether that list contains a cycle.



or

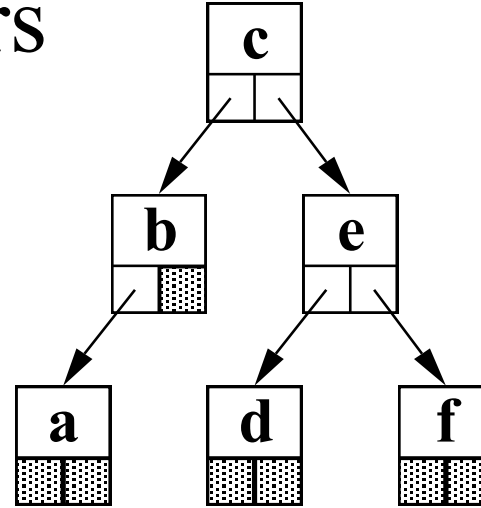


- What approaches fail?
- What techniques work and why?
- Lessons and generalizations

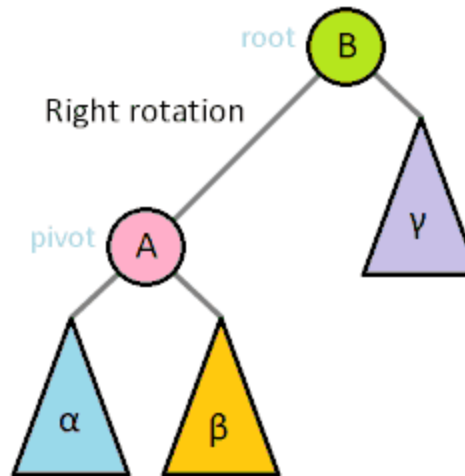


Trees

- Parent/children pointers
- Binary / N-ary
- Ordered / unordered
- Height-balanced:



- B-trees
- AVL trees
- Red-black trees
- 2-3 trees

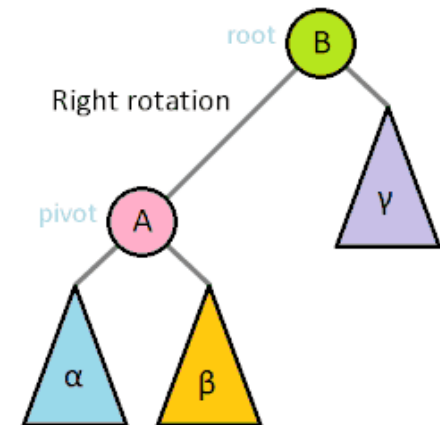


- add / delete / search in $O(\log n)$ time

B-Trees



- Multi-rotations occur infrequently
- Rotations don't propagate far
- Larger tree $\Rightarrow$ fewer rotations
- Same for other height-balanced trees
- Non-balanced search trees **average** $O(\log n)$ height

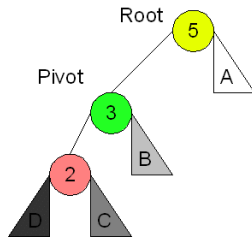


Height-Balanced AVL Trees

There are 4 cases in all, choosing which one is made by seeing the direction of the first 2 nodes from the unbalanced node to the newly inserted node and matching them to the top most row.

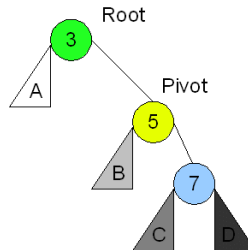
Root is the initial parent before a rotation and **Pivot** is the child to take the root's place.

Left Left Case



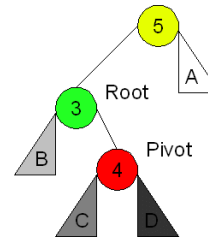
Right Rotation

Right Right Case



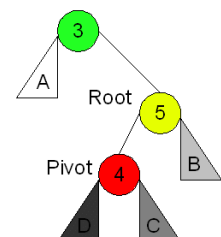
Left Rotation

Left Right Case

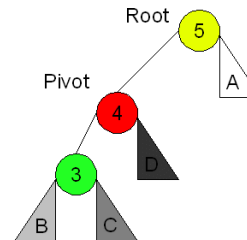
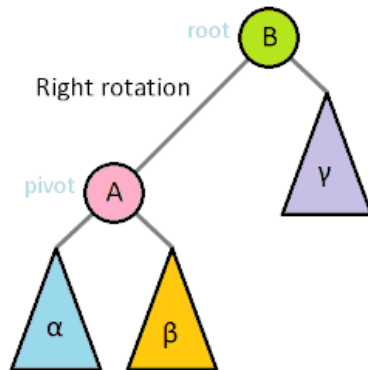


Left Rotation

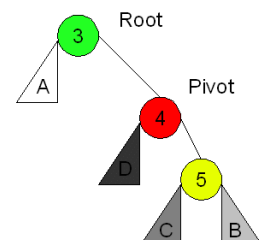
Right Left Case



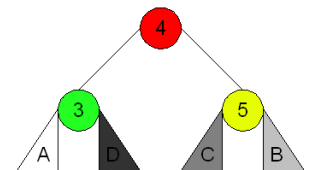
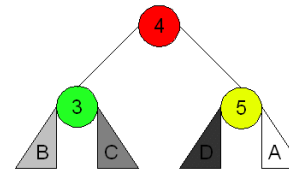
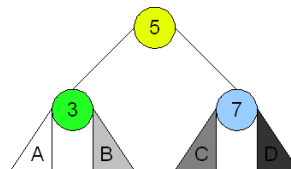
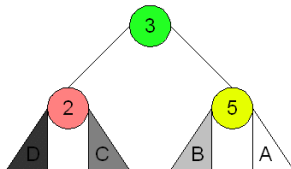
Right Rotation



Right Rotation

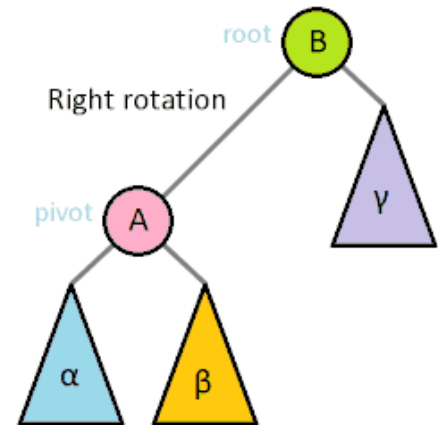


Left Rotation

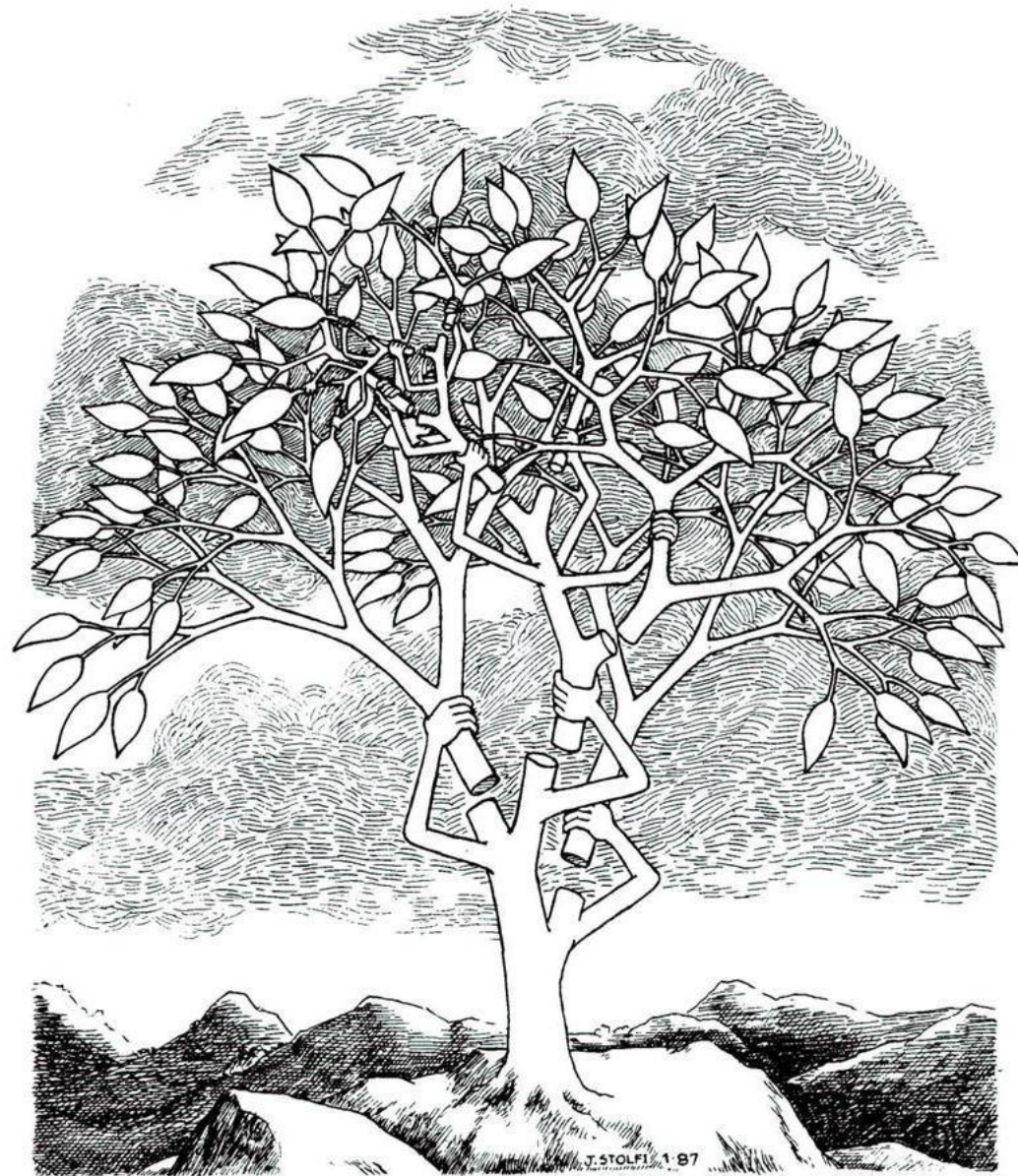
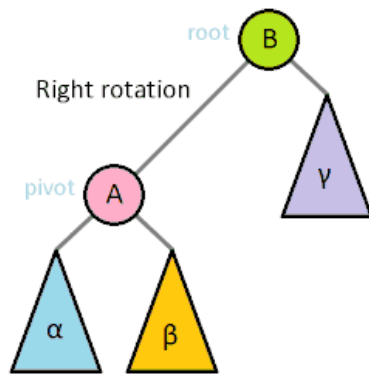


AVL Trees

- Multi-rotations occur infrequently
- Rotations don't propagate far
- Larger tree $\Rightarrow$ fewer rotations
- Same for other height-balanced trees
- Non-balanced trees **average** $O(\log n)$ height



Self-Adjusting Trees

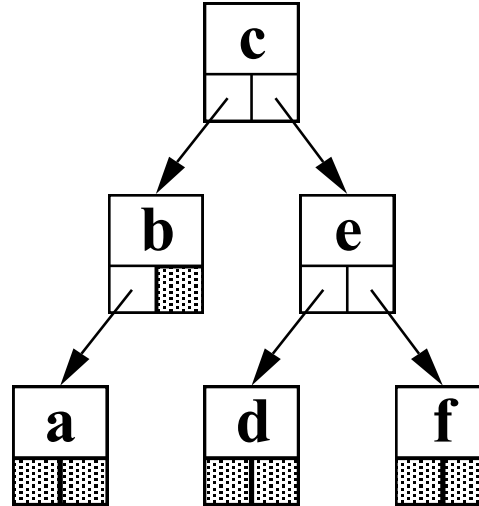


Tree Traversal

- **Pre-order:**

1. process node
2. visit children

⇒ c b a e d f



- **Post-order:**

1. visit children
2. process node

⇒ a b d f e c



- **In-order:**

1. visit left-child
2. process node
3. visit right-child

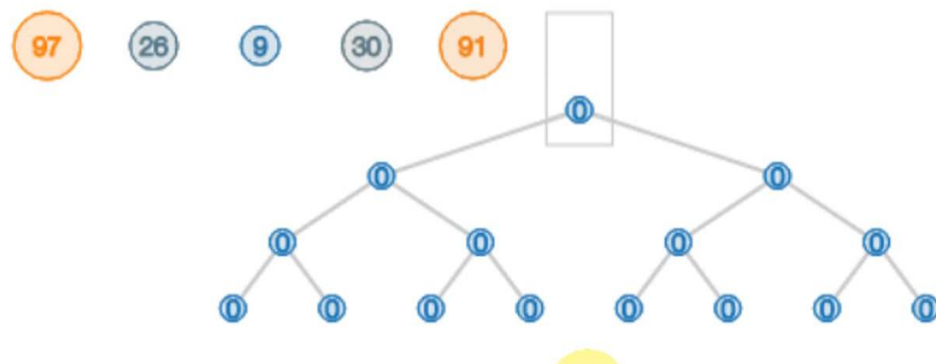
⇒ a b c d e f



Heaps

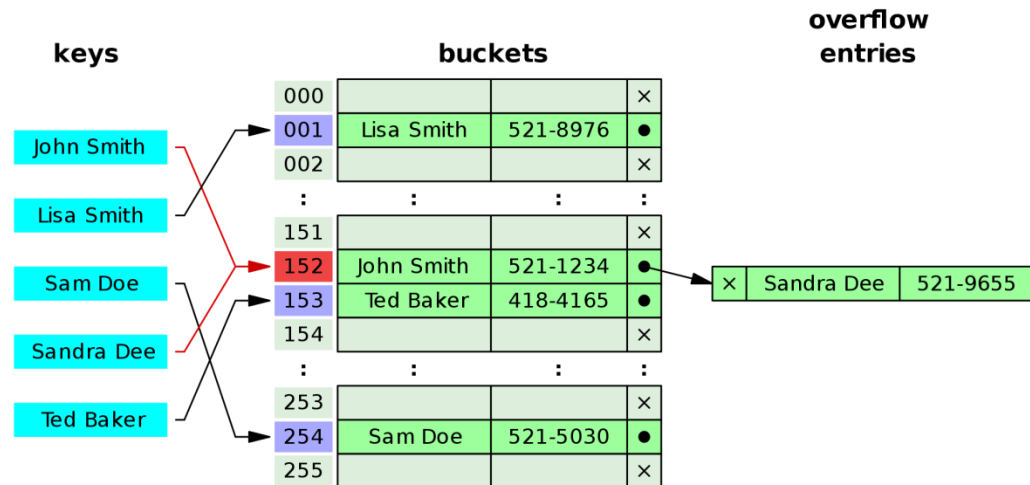
- A tree where all of each node's children have larger / smaller “keys”
- Can be implemented using binary tree or array
- Operations:
 - Find min/max: $O(1)$ time
 - **Add**: $O(\log n)$ time
 - **Delete**: $O(\log n)$ time
 - **Search**: $O(n)$ time

6 5 3 1 8 7 2 4



Hash Tables

- Direct access
- Hash function
- **Collision** resolution:
 - Chaining
 - Linear probing
 - Double hashing
- Universal hashing
- $O(1)$ **average** access
- $O(n)$ worst-case access



Q: Improve **worst-case** access to $O(\log n)$?

3.4 LINEAR PROBING HASH TABLE DEMO



[click to begin demo](#)